

# Solutions and almost solutions of the Gauss equation of $SU(3)/SO(3)$

BY

YOSHIO AGAOKA

*Department of Mathematics, Faculty of Integrated Arts and Sciences,*

*Hiroshima University, Higashi-Hiroshima 739-8521, Japan*

*e-mail: agaoka@mis.hiroshima-u.ac.jp*

## Abstract

We give new solutions and almost solutions of the Gauss equation of the Riemannian symmetric spaces  $SU(3)/SO(3)$  and its non-compact dual in codimensions 4 and 5, which improve the previously known estimates on the codimension. We also give experimental estimates on the infimum of the norm  $\|\gamma_r(\alpha) \pm R\|$  for each codimension  $r$ , where  $R$  is the curvature of  $SU(3)/SO(3)$ , and  $\alpha$  runs all over the space of second fundamental forms.

**Key words:** local isometric imbedding, Riemannian symmetric space, Gauss equation, curvature.

## Introduction.

The explicit determination of the least dimensional Euclidean space into which a given Riemannian manifold  $M$  can be (locally) isometrically immersed is one of the classical fundamental problem in Riemannian geometry. But unfortunately, only a few explicit results are known at present concerning this problem. Even restricting to local isometric imbeddings of Riemannian symmetric spaces, the least dimensional Euclidean spaces are determined only for the spaces  $\mathbf{R}^n$ ,  $S^n$ ,  $H^n$  (the hyperbolic space), [CI]  $Sp(n)/U(n)$  and  $Sp(n)$  (cf. [5], [11], [12]).

To solve this local isometric imbedding problem, it is necessary to determine the least codimension where the Gauss equation admits a solution for a given Riemannian manifold, as a first step problem. In fact, the Gauss equation appears as a first obstruction to the existence of solutions of the differential equations of local isometric imbeddings. But, solving the Gauss equation is in general a hard algebraic problem because it is equivalent to solve a system of real quadratic equations with many equations and many variables, and at present, a little results are obtained for only a special class of Riemannian manifolds. For example, we know that the least codimension is equal to 3 in the case of the Gauss

equation of complex projective space  $M^4 = P^2(\mathbf{C})$  admitting a solution (cf. [2; p.128, 132]). For other results, see the references at the end of this paper.

Now in this paper, we consider the case of 5-dimensional Riemannian symmetric spaces  $SU(3)/SO(3)$  and its non-compact dual, and give a family of solutions of the Gauss equation in codimension 5, which improves the previously known results. In addition, we give “almost solutions” in codimension 4 for both spaces. Here, “almost solutions” imply a family of second fundamental forms  $\alpha_t$  depending on a parameter  $t$  such that the curvature determined by  $\alpha_t$  in terms of the Gauss equation converges to a given curvature, though  $\alpha_t$  itself diverges as  $t$  goes to zero. It is already known that  $SU(3)/SO(3)$  is globally isometrically imbedded into the Euclidean space with codimension 7, and admits a solution of the Gauss equation in codimension 6 (cf. [17]), and this is the best results previously known. Hence, our results in this paper improve the estimates on the codimension where the Gauss equation admits a solution. But in spite of these improvements, it is still an open question which is the “least” codimension where  $SU(3)/SO(3)$  (or its dual) is locally isometrically immersed. It is our next problem whether the second fundamental forms we construct in this paper are the actual second fundamental forms for some local isometric imbeddings of  $SU(3)/SO(3)$  (or its dual) into  $\mathbf{R}^{10}$ .

To obtain the results of this paper, computational experiments by the software Mathematica are quite useful in finding solutions and almost solutions. At the end of this paper, we add some numerical estimates on the infimum of the norm  $\|\gamma_r(\alpha) \pm R\|$  for each codimension  $r$ , where  $R$  is the curvature of  $SU(3)/SO(3)$ , and  $\alpha$  runs all over the space of second fundamental forms. These results suggest that the least codimension such that the Gauss equation admits a solution is 4 or 5 for both spaces.

### § 1. Curvature of $SU(3)/SO(3)$ and the main theorem.

We first write down the curvature of the space  $SU(3)/SO(3)$ . We put  $\mathfrak{g} = \mathfrak{su}(3)$ ,  $\mathfrak{k} = \mathfrak{o}(3)$  and

$$\mathfrak{m} = \left\{ i \begin{pmatrix} a & p & q \\ p & b & r \\ q & r & c \end{pmatrix} \mid \begin{array}{l} a, b, c, p, q, r \in \mathbf{R}, \\ a + b + c = 0 \end{array} \right\}.$$

Then, we have the canonical decomposition  $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{m}$  of  $SU(3)/SO(3)$ , and the space  $\mathfrak{m}$  may be considered as the tangent space of  $SU(3)/SO(3)$  at the origin. The bi-invariant metric of  $SU(3)/SO(3)$  is given by  $\langle X, Y \rangle = -1/2 \cdot \text{Tr } XY$  ( $X, Y \in \mathfrak{m}$ ), and the curvature of this metric is given by

$$R(X, Y, Z, W) = -1/2 \cdot \text{Tr } [X, Y][Z, W].$$

We fix the orthonormal basis  $\{X_1, \dots, X_5\}$  of  $\mathfrak{m}$  by

$$X_1 = \begin{pmatrix} i & & \\ & 0 & \\ & & -i \end{pmatrix}, \quad X_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} i & & \\ & -2i & \\ & & i \end{pmatrix}, \quad X_3 = \begin{pmatrix} 0 & i & \\ i & 0 & \\ & & 0 \end{pmatrix},$$

$$X_4 = \begin{pmatrix} 0 & i \\ 0 & 0 \\ i & 0 \end{pmatrix}, \quad X_5 = \begin{pmatrix} 0 & 0 \\ 0 & i \\ i & 0 \end{pmatrix}.$$

Then the components of the curvature tensor are explicitly given by

$$\begin{aligned} R_{1313} &= R_{1345} = R_{1515} = R_{1534} = R_{3434} = R_{3535} = R_{4545} = 1, \\ R_{1323} &= R_{2345} = \sqrt{3}, \quad R_{1525} = R_{2534} = -\sqrt{3}, \\ R_{1435} &= 2, \quad R_{2323} = R_{2525} = 3, \\ R_{1414} &= 4, \end{aligned}$$

and other  $R_{ijkl} = 0$  except for the components obtained by the symmetric property

$$R_{ijkl} = R_{klij} = -R_{jikl} = -R_{ijlk},$$

where  $R_{ijkl}$  is one of the above (cf. [2; p.129]). The curvature of the non-compact dual space of  $SU(3)/SO(3)$  is given by  $-R$ .

Let  $K$  be the space of curvature like tensors on  $\mathfrak{m}$ , i.e.,

$$K = \{R \in \wedge^2 \mathfrak{m}^* \otimes \wedge^2 \mathfrak{m}^* \mid \mathfrak{S}_{X,Y,Z} R(X, Y, Z, W) = 0\}.$$

We define a quadratic map

$$\gamma_r : S^2 \mathfrak{m}^* \otimes \mathbf{R}^r \longrightarrow K$$

by

$$\gamma_r(\alpha)(X, Y, Z, W) = \langle \alpha(X, Z), \alpha(Y, W) \rangle - \langle \alpha(X, W), \alpha(Y, Z) \rangle$$

for  $\alpha \in S^2 \mathfrak{m}^* \otimes \mathbf{R}^r$ ,  $X, Y, Z, W \in \mathfrak{m}$ , and denote the image of this map by  $\text{Im } \gamma_r$ . The image  $\text{Im } \gamma_r$  is not in general closed in  $K$  (cf. [2; p.134]), and we denote its Zariski closure by  $\overline{\text{Im } \gamma_r}$ . The space  $S^2 \mathfrak{m}^* \otimes \mathbf{R}^r$  indicates the space of pointwise second fundamental forms of submanifolds with codimension  $r$ . Then, the Gauss equation of  $SU(3)/SO(3)$  (and its dual) with codimension  $r$  is expressed as

$$\gamma_r(\alpha) = \pm R,$$

where  $R$  is the curvature of  $SU(3)/SO(3)$  stated above. Clearly, the Gauss equation admits a solution if and only if  $R \in \text{Im } \gamma_r$  (or  $-R \in \text{Im } \gamma_r$ , in the dual case). In particular, if we can prove  $R \notin \text{Im } \gamma_r$  (or  $-R \notin \text{Im } \gamma_r$ ) for some  $r$ , then it follows that  $SU(3)/SO(3)$  (or its dual) cannot be isometrically immersed into the Euclidean space with codimension  $r$  even locally.

Concerning the existence or non-existence of the solutions of the Gauss equation of  $SU(3)/SO(3)$  and its non-compact dual, we have the following results, which is the main theorem of this paper.



$$\begin{aligned}
a_1a_2 + b_1b_2 &= a_6^2 + b_6^2, & c_1c_3 &= 1, \\
a_1a_3 + b_1b_3 &= c_1^2 + 1, & c_2c_3 &= d_2d_3, \\
a_1a_4 + b_1b_4 &= 4, & d_1d_3 &= -1, \\
a_1a_5 + b_1b_5 &= d_1^2 + 1, & d_2d_3 &= e_1e_2 - \sqrt{3}, \\
a_2a_3 + b_2b_3 &= c_2^2 + 3, \\
a_2a_4 + b_2b_4 &= e_1^2, \\
a_2a_5 + b_2b_5 &= d_2^2 + 3, \\
a_3a_4 + b_3b_4 &= d_3^2 + 1, \\
a_3a_5 + b_3b_5 &= e_2^2 + 1, \\
a_3a_6 + b_3b_6 &= c_1c_2 + \sqrt{3}, \\
a_4a_5 + b_4b_5 &= c_3^2 + 1, \\
a_4a_6 + b_4b_6 &= 0, \\
a_5a_6 + b_5b_6 &= d_1d_2 - \sqrt{3}.
\end{aligned}$$

This system of equations admits a family of solutions

$$\begin{aligned}
a_1 &= a, & b_1 &= b, \\
a_2 &= -\frac{bd}{a}, & b_2 &= d, \\
a_3 &= a_5 = -\frac{a(3b - c^2d)}{c^2d(c^2 + 1)}, & b_3 &= b_5 = \frac{3a^2 + bc^2d}{c^2d(c^2 + 1)}, \\
a_4 &= \frac{12a^2 - bd(c^2 - 1)^2}{3a(c^2 + 1)^2}, & b_4 &= \frac{12b + d(c^2 - 1)^2}{3(c^2 + 1)^2}, \\
a_6 &= 0, & b_6 &= 0, \\
c_1 &= c, & d_1 &= c, & e_1 &= \frac{\sqrt{3}d(c^2 - 1)}{3a}, \\
c_2 &= -\frac{\sqrt{3}}{c}, & d_2 &= \frac{\sqrt{3}}{c}, & e_2 &= \frac{3a}{c^2d}, \\
c_3 &= \frac{1}{c}, & d_3 &= -\frac{1}{c},
\end{aligned}$$

where  $a, b, c, d$  are real numbers satisfying the conditions

$$a^2 + b^2 = (c^2 + 1)^2, \quad a \neq 0, \quad c \neq 0, \quad d \neq 0.$$

Next, we construct almost solutions of  $SU(3)/SO(3)$  in codimension 4. We put  $\alpha_5 = 0$  (i.e.,  $e_1 = e_2 = 0$ ) in the above notations. Then, we have  $\alpha \in S^2\mathfrak{m}^* \otimes \mathbf{R}^4$ . In addition, we set  $c = 1$  in the above solutions of the Gauss equation. Then we have

$$\begin{aligned}
a_1 = a_4 = a, & & b_1 = b_4 = b, \\
a_2 = -\frac{bd}{a}, & & b_2 = d, \\
a_3 = a_5 = -\frac{a(3b-d)}{2d}, & & b_3 = b_5 = \frac{3a^2 + bd}{2d}, \\
a_6 = 0, & & b_6 = 0, \\
c_1 = 1, & & d_1 = 1, \\
c_2 = -\sqrt{3}, & & d_2 = \sqrt{3}, \\
c_3 = 1, & & d_3 = -1,
\end{aligned}$$

where  $a, b, d$  are real numbers satisfying the conditions

$$a^2 + b^2 = 4, \quad a \neq 0, \quad d \neq 0.$$

In this situation, we have

$$(\gamma_4(\alpha) - R)_{3535} = \left(\frac{3a}{d}\right)^2,$$

and remaining components of  $\gamma_4(\alpha) - R \in K$  are all zero. Hence, by putting  $a \rightarrow 0$ , we have  $\gamma_4(\alpha) \rightarrow R$ , which implies  $R \in \text{Im } \gamma_4$ .

Next, we consider the non-compact dual of  $SU(3)/SO(3)$ . We construct a family of solutions of the Gauss equation in codimension 5. We use the same notations as in the case of  $SU(3)/SO(3)$  with codimension 5. Then  $\alpha = (\alpha_1, \dots, \alpha_5)$  is the solution of the Gauss equation  $\gamma_5(\alpha) + R = 0$  if and only if

$$\begin{aligned}
a_1 a_2 + b_1 b_2 &= a_6^2 + b_6^2, & c_1 c_3 &= -1, \\
a_1 a_3 + b_1 b_3 &= c_1^2 - 1, & c_2 c_3 &= d_2 d_3, \\
a_1 a_4 + b_1 b_4 &= -4, & d_1 d_3 &= 1, \\
a_1 a_5 + b_1 b_5 &= d_1^2 - 1, & d_2 d_3 &= \epsilon_1 \epsilon_2 + \sqrt{3}, \\
a_2 a_3 + b_2 b_3 &= c_2^2 - 3, \\
a_2 a_4 + b_2 b_4 &= e_1^2, \\
a_2 a_5 + b_2 b_5 &= d_2^2 - 3, \\
a_3 a_4 + b_3 b_4 &= d_3^2 - 1, \\
a_3 a_5 + b_3 b_5 &= e_2^2 - 1, \\
a_3 a_6 + b_3 b_6 &= c_1 c_2 - \sqrt{3}, \\
a_4 a_5 + b_4 b_5 &= c_3^2 - 1, \\
a_4 a_6 + b_4 b_6 &= 0, \\
a_5 a_6 + b_5 b_6 &= d_1 d_2 + \sqrt{3}.
\end{aligned}$$

This system admits a family of solutions

$$\begin{aligned}
a_1 &= a, & b_1 &= b, \\
a_2 &= -\frac{bd}{a}, & b_2 &= d, \\
a_3 = a_5 &= \frac{a(3b + c^2d)(c^2 - 1)}{c^2d(a^2 + b^2)}, & b_3 = b_5 &= -\frac{(3a^2 - bc^2d)(c^2 - 1)}{c^2d(a^2 + b^2)}, \\
a_4 &= -\frac{4a(3b + c^2d)}{c^2d(a^2 + b^2)}, & b_4 &= \frac{4(3a^2 - bc^2d)}{c^2d(a^2 + b^2)}, \\
a_6 &= 0, & b_6 &= 0, \\
c_1 &= c, & d_1 &= c, & e_1 &= -\frac{2\sqrt{3}}{c}, \\
c_2 &= \frac{\sqrt{3}}{c}, & d_2 &= -\frac{\sqrt{3}}{c}, & e_2 &= \frac{c^2 + 1}{2c}, \\
c_3 &= -\frac{1}{c}, & d_3 &= \frac{1}{c},
\end{aligned}$$

where  $a, b, c, d$  are real numbers satisfying the conditions

$$a^2 + b^2 > 4c^2, \quad a \neq 0, \quad c \neq 0, \quad d = \pm \frac{6a}{c\sqrt{a^2 + b^2 - 4c^2}}.$$

Next, we construct almost solutions in codimension 4. In the above notations, we assume  $\alpha_5 = 0$  (i.e.,  $e_1 = e_2 = 0$ ), and put

$$\begin{aligned}
a_1 &= \frac{4a}{a^2 - 1}, & b_1 &= \frac{b}{t}, & c_1 &= -\frac{1}{a}, \\
a_2 &= 0, & b_2 &= \frac{3b(a^2 - 1)^2}{t(a^2 + 1)^2}, & c_2 &= \frac{\sqrt{3}}{a}, \\
a_3 &= \frac{1}{a}, & b_3 &= -\frac{t(a^2 + 1)^2}{a^2b(a^2 - 1)}, & c_3 &= a, \\
a_4 &= -\frac{a^2 - 1}{a}, & b_4 &= 0, & d_1 &= a, \\
a_5 &= -a, & b_5 &= \frac{t(a^2 + 1)^2}{b(a^2 - 1)}, & d_2 &= \sqrt{3}a, \\
a_6 &= t, & b_6 &= \frac{\sqrt{3}b(a^2 - 1)}{t(a^2 + 1)}, & d_3 &= \frac{1}{a},
\end{aligned}$$

where  $a, b$  and  $t$  are real numbers satisfying the conditions

$$a \neq 0, \pm 1, \quad b \neq 0, \quad t \neq 0.$$

Then, we have

$$\begin{aligned}
(\gamma_4(\alpha) + R)_{1212} &= -t^2, & (\gamma_4(\alpha) + R)_{1525} &= -at, \\
(\gamma_4(\alpha) + R)_{1323} &= \frac{t}{a}, & (\gamma_4(\alpha) + R)_{3535} &= -\frac{t^2(a^2 + 1)^4}{a^2b^2(a^2 - 1)^2}, \\
(\gamma_4(\alpha) + R)_{1424} &= -\frac{t(a^2 - 1)}{a},
\end{aligned}$$

and remaining components of  $\gamma_4(\alpha) + R$  are all zero. Hence, by putting  $t \rightarrow 0$ , we have  $\gamma_4(\alpha) \rightarrow -R$ , and hence we have  $-R \in \overline{\text{Im}} \gamma_4$ . q.e.d.

### § 3. Remarks.

(1) The space  $\mathfrak{m}^*$  is a 5-dimensional irreducible representation space of the isotropy group of  $SU(3)/SO(3)$ . Its symmetric 2-product  $S^2\mathfrak{m}^*$  is decomposed into three  $SO(3)$ -irreducible components with dimensions 9, 5 and 1, respectively. Among them, the 5-dimensional irreducible subspace of  $S^2\mathfrak{m}^*$  consists of matrices of the form

$$\begin{pmatrix} 2p_1 & 4p_2 & \sqrt{3}p_3 & 0 & \sqrt{3}p_4 \\ 4p_2 & -2p_1 & -p_3 & 2p_5 & p_4 \\ \sqrt{3}p_3 & -p_3 & -p_1 + \sqrt{3}p_2 & -\sqrt{3}p_4 & \sqrt{3}p_5 \\ 0 & 2p_5 & -\sqrt{3}p_4 & 2p_1 & \sqrt{3}p_3 \\ \sqrt{3}p_4 & p_4 & \sqrt{3}p_5 & \sqrt{3}p_3 & -p_1 - \sqrt{3}p_2 \end{pmatrix}, \quad p_i \in \mathbf{R},$$

where we express the element of  $S^2\mathfrak{m}^*$  as a symmetric matrix by using the orthonormal basis  $X_1, \dots, X_5$  of  $\mathfrak{m}$  which we defined before. Clearly, the second fundamental forms  $\alpha$  which we constructed in §2 have a strong resemblance to this 5-dimensional irreducible subspace if we ignore the coefficients of  $p_i$ . We do not know whether we can construct a low codimensional solution of the Gauss equation for general  $SU(m)/SO(m)$  ( $m \geq 4$ ) by applying the similar principle to some  $SO(m)$ -irreducible subspace of  $S^2\mathfrak{m}^*$ . (For general  $m$ , it is already known that the space  $SU(m)/SO(m)$  is globally isometrically imbedded into the Euclidean space with codimension  $1/2 \cdot (m^2 + m + 2)$ , but does not admit a solution of the Gauss equation in codimension  $1/2 \cdot (m^2 - m - 2)$ . Hence it cannot be isometrically immersed into this codimensional Euclidean space even locally (cf. [17], [11]). Note that there still remains a gap of linear order on  $m$  between these two codimensions.)

(2) In general, the image of a polynomial map between two vector spaces is not closed, as stated before. And this phenomenon sometimes implies the existence of "almost solutions" of a system of polynomial equations. A similar phenomenon occurs in the case of left invariant torsion free flat affine connections on homogeneous spaces (cf. [6], [7], [8]). In this case, the map we consider is

$$\gamma : \{\text{left invariant torsion free affine connection}\} \longrightarrow \{\text{curvature}\},$$

which is also quadratic. The examples stated in [6], [7], [8] imply that the image of this map is not closed for the case of the three dimensional sphere. In fact, this space admits an almost flat affine structure, though it never possess torsion free flat affine connections. Our examples of almost solutions of the Gauss equation given in this paper have the same origin as in the case of this almost flat affine structure.

(3) The norms of  $R$  and  $-R$  are given by

$$\|R\|^2 = \|-R\|^2 = \sum_{i < j, k < l} (R_{ijkl})^2 = 75.$$



By modifying  $R$  (or  $-R$ ) by second fundamental forms  $\gamma_r(\alpha)$ , we can decrease these values. Numerical calculations by the software Mathematica, combined with the results (2) in Theorem, we have

$$\begin{aligned} \inf_{\alpha} \|\gamma_1(\alpha) - R\|^2 &\leq 52.45, & \inf_{\alpha} \|\gamma_1(\alpha) + R\|^2 &\leq 57.01, \\ \inf_{\alpha} \|\gamma_2(\alpha) - R\|^2 &\leq 36.01, & \inf_{\alpha} \|\gamma_2(\alpha) + R\|^2 &\leq 39.04, \\ \inf_{\alpha} \|\gamma_3(\alpha) - R\|^2 &\leq 13.49, & \inf_{\alpha} \|\gamma_3(\alpha) + R\|^2 &\leq 15.92, \\ \inf_{\alpha} \|\gamma_4(\alpha) - R\|^2 &= 0, & \inf_{\alpha} \|\gamma_4(\alpha) + R\|^2 &= 0, \end{aligned}$$

where  $\alpha$  runs all over the space  $S^2\mathfrak{m}^* \otimes \mathbf{R}^r$  for each  $r$ . Precise infimums for the cases  $r = 1, 2, 3$  are not yet determined. But these results suggest that the least codimension where the Gauss equation admits a solution is 4 or 5 for  $SU(3)/SO(3)$  and its dual.

By calculating the rank of the differential of  $\gamma_r$  at a generic point  $\alpha$ , we know that there exists an obstruction to the existence of the solutions of the Gauss equation for the case  $M^5 \subset \mathbf{R}^8$ , which is a covariant of the curvature tensor (cf. [9]). Unfortunately, we do not know its explicit form yet. If the explicit form of the covariant is obtained, it may be possible to show that  $\pm R \notin \text{Im } \gamma_3$  by using this covariant. But, in the 4-codimensional case, it seems quite difficult to show the “non-existence” of solutions of the Gauss equation, unless we discover essentially new devices.

(4) It is an important problem whether the 5-codimensional solutions which we construct in this paper are the actual second fundamental forms for some local isometric imbeddings of  $SU(3)/SO(3)$  (or its dual) into  $\mathbf{R}^{10}$ . It is desirable to investigate this problem by the similar method as in the case of  $P^2(\mathbf{C}) \subset \mathbf{R}^7$  treated in Kaneda [16], though it requires tremendous calculations on prolongations.

(5) We consider  $\|\gamma_r(\alpha) \pm R\|^2$  as functions on the space  $S^2\mathfrak{m}^* \otimes \mathbf{R}^r$ . Then, it is an interesting problem to find the critical points of these functions. Certainly,  $\mathbf{R}^r$ -valued symmetric forms corresponding to these critical points have some intrinsic geometric meaning, though the explicit determination of critical points seems to be quite difficult.

### References

- [1] Y. Agaoka, *Isometric immersions of  $SO(5)$* , J. Math. Kyoto Univ. **24** (1984), 713-724.
- [2] Y. Agaoka, *On the curvature of Riemannian submanifolds of codimension 2*, Hokkaido Math. J. **14** (1985), 107-135.
- [3] Y. Agaoka, *A note on local isometric imbeddings of complex projective spaces*, J. Math. Kyoto Univ. **27** (1987), 501-505.
- [4] Y. Agaoka, *Generalized Gauss equations*, Hokkaido Math. J. **20** (1991), 1-44.
- [5] Y. Agaoka, *A table on the codimension of local isometric imbeddings of Riemannian symmetric spaces*, Mem. Fac. Integrated Arts and Sci., Hiroshima Univ., Ser.IV, Science Report **18** (1992), 1-10.

- [6] Y. Agaoka, *On the curvature of the homogeneous space  $U(n+1)/U(n)$* , Mem. Fac. Integrated Arts and Sci., Hiroshima Univ., Ser.IV, Science Report **19** (1993), 1-17.
- [7] Y. Agaoka, *An example of almost flat affine connections on the three-dimensional sphere*, Proc. Amer. Math. Soc. **123** (1995), 3519-3521.
- [8] Y. Agaoka, *A new example of higher order almost flat affine connections on the three-dimensional sphere*, Houston J. Math. **24** (1998), 387-396; Errata, ibid **24** (1998), 759.
- [9] Y. Agaoka, *On the rank of the Gauss equation*, in preparation.
- [10] Y. Agaoka and E. Kaneda, *On local isometric immersions of Riemannian symmetric spaces*, Tôhoku Math. J. **36** (1984), 107-140.
- [11] Y. Agaoka and E. Kaneda, *An estimate on the codimension of local isometric imbeddings of compact Lie groups*, Hiroshima Math. J. **24** (1994), 77-110.
- [12] Y. Agaoka and E. Kaneda, *Local isometric imbeddings of symplectic groups*, Geometriae Dedicata **71** (1998), 75-82.
- [13] Y. Agaoka and E. Kaneda, *Local isometric imbeddings of Grassmann manifolds*, in preparation.
- [14] H. Jacobowitz, *Curvature operators on the exterior algebra*, Linear and Multilinear Algebra **7** (1979), 93-105.
- [15] E. Kaneda, *On local isometric immersions of the spaces of negative constant curvature into the euclidean spaces*, J. Math. Kyoto Univ. **19** (1979), 269-284.
- [16] E. Kaneda, *On the Gauss-Codazzi equations*, Hokkaido Math. J. **19** (1990), 189-213.
- [17] S. Kobayashi, *Isometric imbeddings of compact symmetric spaces*, Tôhoku Math. J. **20** (1968), 21-25.
- [18] M. Matsumoto, *Local imbedding of Riemannian spaces I, II*, Sûgaku **5** (1953), 210-219; **6** (1954), 6-16, (in Japanese).
- [19] T. Y. Thomas, *Riemann spaces of class one and their characterization*, Acta Math. **67** (1935), 169-211.
- [20] J. Vilms, *Local isometric imbedding of Riemannian  $n$ -manifolds into Euclidean  $(n+1)$ -space*, J. Diff. Geom. **12** (1977), 197-202.