

**A deterministic two-way multi-head
finite automaton can be converted
into a reversible one with the
same number of heads**

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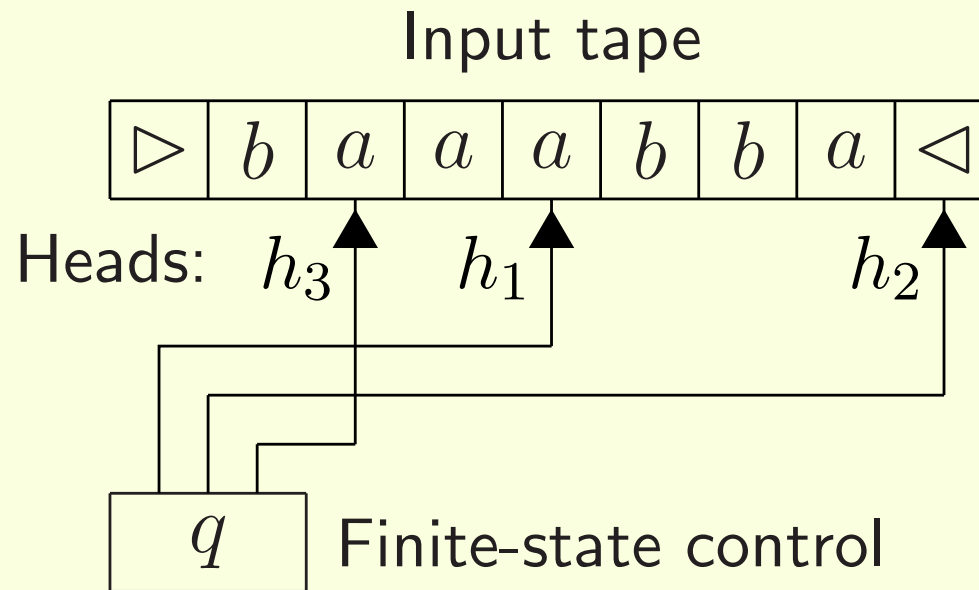
1. Introduction:
A multi-head finite automaton (MFA)
2. Converting a deterministic MFA into a reversible one
3. Applying the conversion method to Turing machines

1. Introduction:

A multi-head finite automaton

Multi-head finite automaton (MFA)

- It is a simple classical model of an acceptor for a formal language.
- It consists of a finite-state control, an input tape, and k read-only heads (MFA(k)).



Past studies on reversible MFAs

- A two-way reversible MFA was introduced, and its basic properties were shown. [Morita, 2011]
- The class of two-way reversible MFAs is exactly characterized by the class of deterministic (and reversible) logarithmic space. [Axelsen, 2012]
- A one-way reversible MFA was studied, and its accepting capability was investigated.
[Kutrib, Malcher, 2012]

Formal definition of a two-way MFA(k)

$$M = (Q, \Sigma, k, \delta, \triangleright, \triangleleft, q_0, A, R)$$

- Q : a nonempty finite set of states
- Σ : a nonempty finite set of input symbols
- k : a number of heads ($k \in \{1, 2, \dots\}$)
- $\triangleright, \triangleleft$: left and right endmarkers ($\triangleright, \triangleleft \notin \Sigma$)
- q_0 : the initial state ($q_0 \in Q$)
- A : a set of accepting states ($A \subset Q$)
- R : a set of rejecting states ($R \subset Q, A \cap R = \emptyset$)
- δ : a transition relation, which is a subset of $Q \times ((\Sigma \cup \{\triangleright, \triangleleft\})^k \cup \{-1, 0, +1\}^k) \times Q$

The transition relation δ of an MFA(k)

- δ is a set of “triples” of the form $[p, \mathbf{x}, q]$.
 - p : a present state ($p \in Q$)
 - \mathbf{x} : symbols read ($\mathbf{x} \in (\Sigma \cup \{\triangleright, \triangleleft\})^k$), or shift directions ($\mathbf{x} \in \{-1, 0, +1\}^k$)
 - q : a next state ($q \in Q$)
- $[p, \mathbf{s}, q]$ is called a **read-rule** if $\mathbf{s} \in (\Sigma \cup \{\triangleright, \triangleleft\})^k$.
- $[p, \mathbf{d}, q]$ is called a **shift-rule** if $\mathbf{d} \in \{-1, 0, +1\}^k$.

Note: Quintuple formulation is also used: $[p, \mathbf{s}, \mathbf{d}, q]$

Determinism of an MFA M

- An MFA M is called a **deterministic MFA** iff

$$\begin{aligned} &\forall r_1 = [p, x, q] \in \delta, \forall r_2 = [p', x', q'] \in \delta \\ &((r_1 \neq r_2 \wedge p = p') \Rightarrow \\ & \quad (x \notin \{-1, 0, +1\}^k \wedge x' \notin \{-1, 0, +1\}^k \\ & \quad \wedge x \neq x')) \end{aligned}$$

- It means that for every pair of rules r_1 and r_2 , if the present states of them are the same, then
 - (1) r_1 and r_2 must be read-rules, and
 - (2) the symbols x and x' must be different.

Reversibility of an MFA M

- An MFA M is called a **reversible MFA** iff

$$\begin{aligned} &\forall r_1 = [p, \mathbf{x}, q] \in \delta, \forall r_2 = [p', \mathbf{x}', q'] \in \delta \\ &((r_1 \neq r_2 \wedge q = q') \Rightarrow \\ &(\mathbf{x} \notin \{-1, 0, +1\}^k \wedge \mathbf{x}' \notin \{-1, 0, +1\}^k \\ &\wedge \mathbf{x} \neq \mathbf{x}')) \end{aligned}$$

- It means that for every pair of rules r_1 and r_2 , if the next states of them are the same, then
 - (1) r_1 and r_2 must be read-rules, and
 - (2) the symbols \mathbf{x} and \mathbf{x}' must be different.

Notations for deterministic and reversible MFAs

- DMFA: Irreversible and deterministic MFA.
- RDMFA: Reversible and deterministic MFA.
- DMFA(k): DMFA with k heads.
- RDMFA(k): RDMFA with k heads.

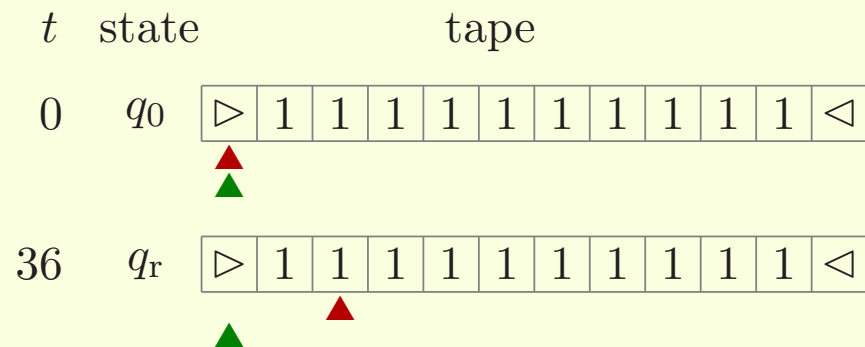
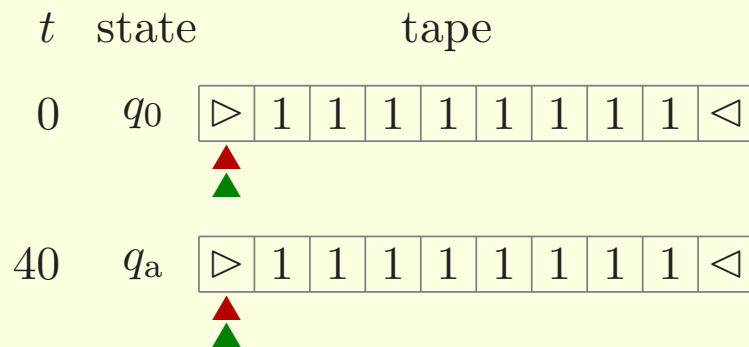
Note: We do not consider a nondeterministic MFA hereafter.

Example: An RMFA(2) that accepts all strings of length 2^m ($m = 0, 1, \dots$) [Morita, 2011]

$$M_{2^m} = (\{q_0, q_1, \dots, q_5, q_a, q_r\}, \{1\}, 2, \delta_{2^m}, \triangleright, \triangleleft, q_0, \{q_a\}, \{q_r\})$$

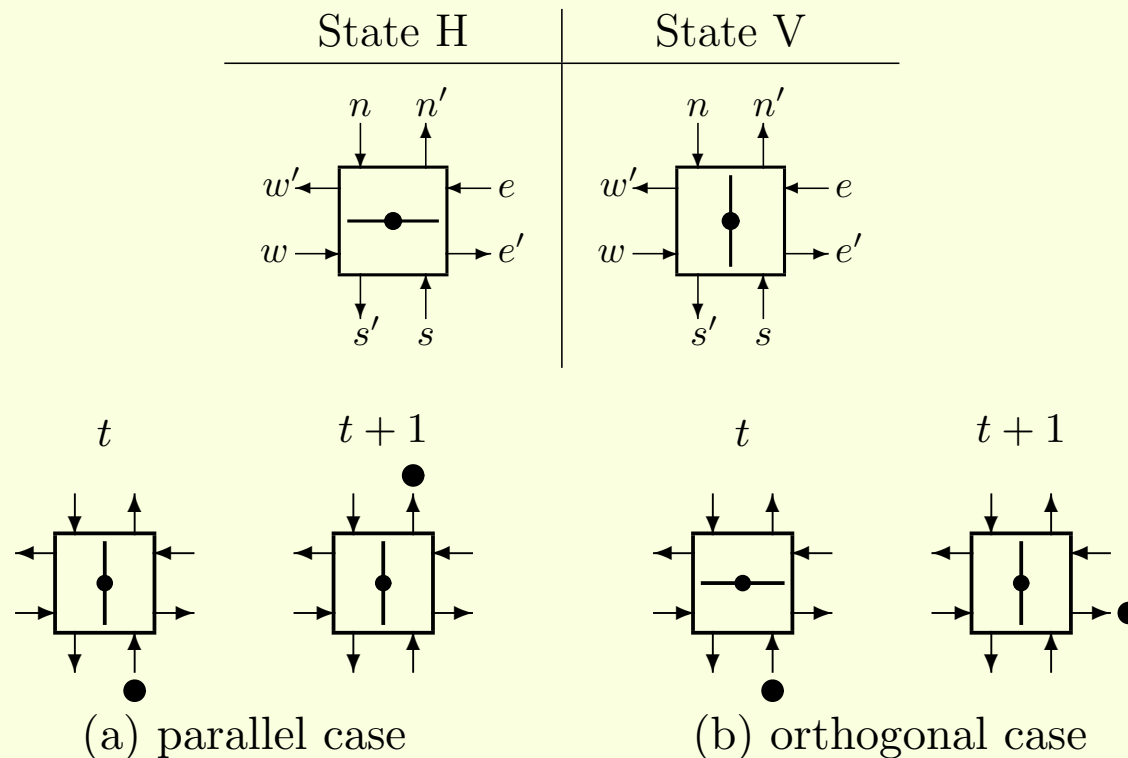
$$\delta_{2^m} = \{ [q_0, [\triangleright, \triangleright], [0, +], q_1], [q_1, [\triangleright, 1], [0, +], q_1], [q_1, [\triangleright, \triangleleft], [+,-], q_2], [q_2, [1, 1], [0, -], q_3], [q_2, [1, \triangleright], [-,+], q_4], [q_2, [\triangleleft, \triangleright], [0, 0], q_r], [q_3, [1, 1], [+,-], q_2], [q_3, [1, \triangleright], [-, 0], q_5], [q_4, [1, 1], [-,+], q_4], [q_4, [\triangleright, 1], [+,-], q_2], [q_5, [\triangleright, \triangleright], [0, 0], q_a], [q_5, [1, \triangleright], [0, 0], q_r] \}$$

- M_{2^m} divides n by 2 repeatedly and checks if the remainders are all 0s till the dividend becomes 1.



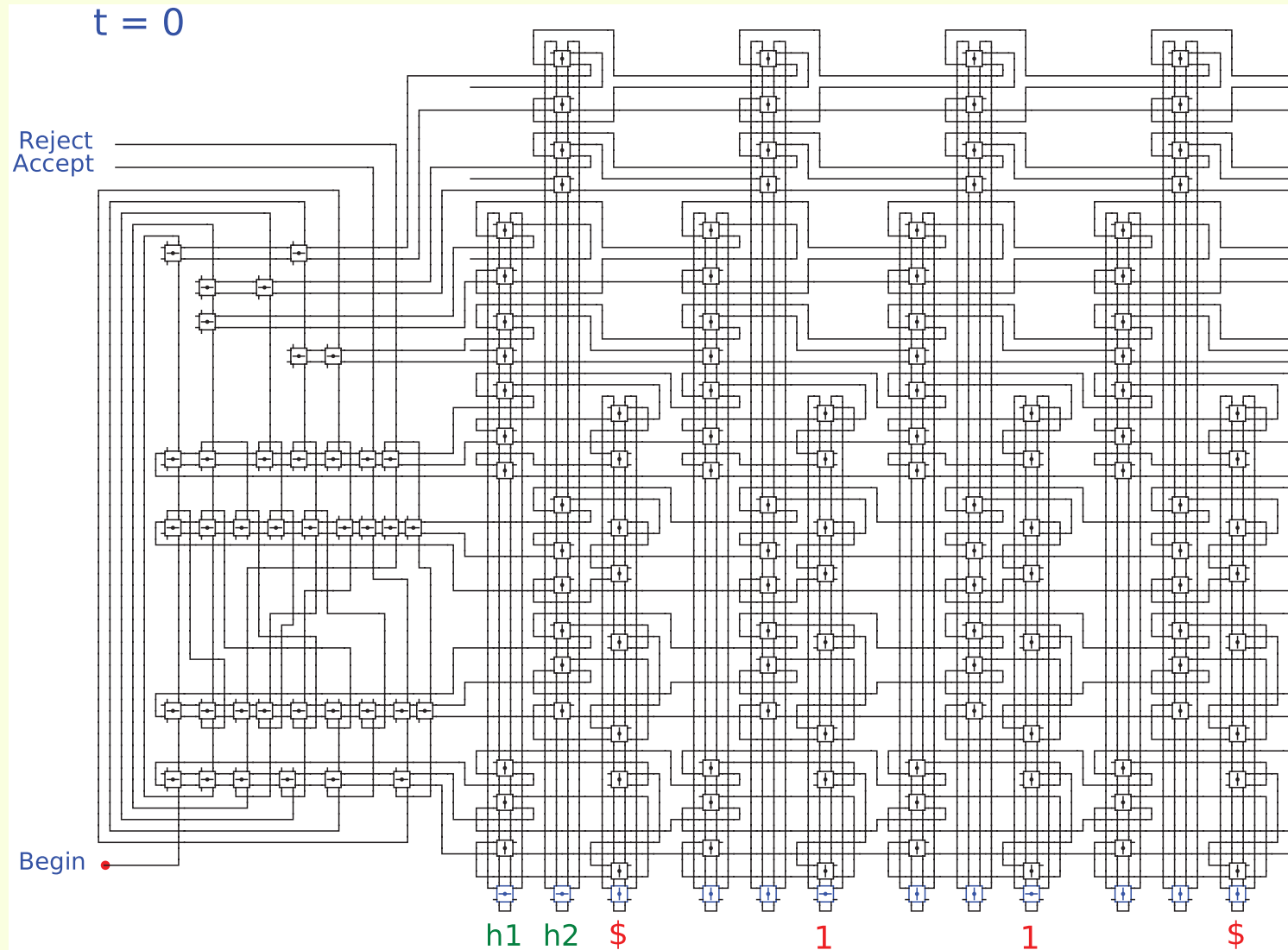
An RDMFA can be realized as a garbage-less reversible logic circuit

- A rotary element (RE) is a reversible logic element with 2 states and 4 symbols. [Morita, 2001]



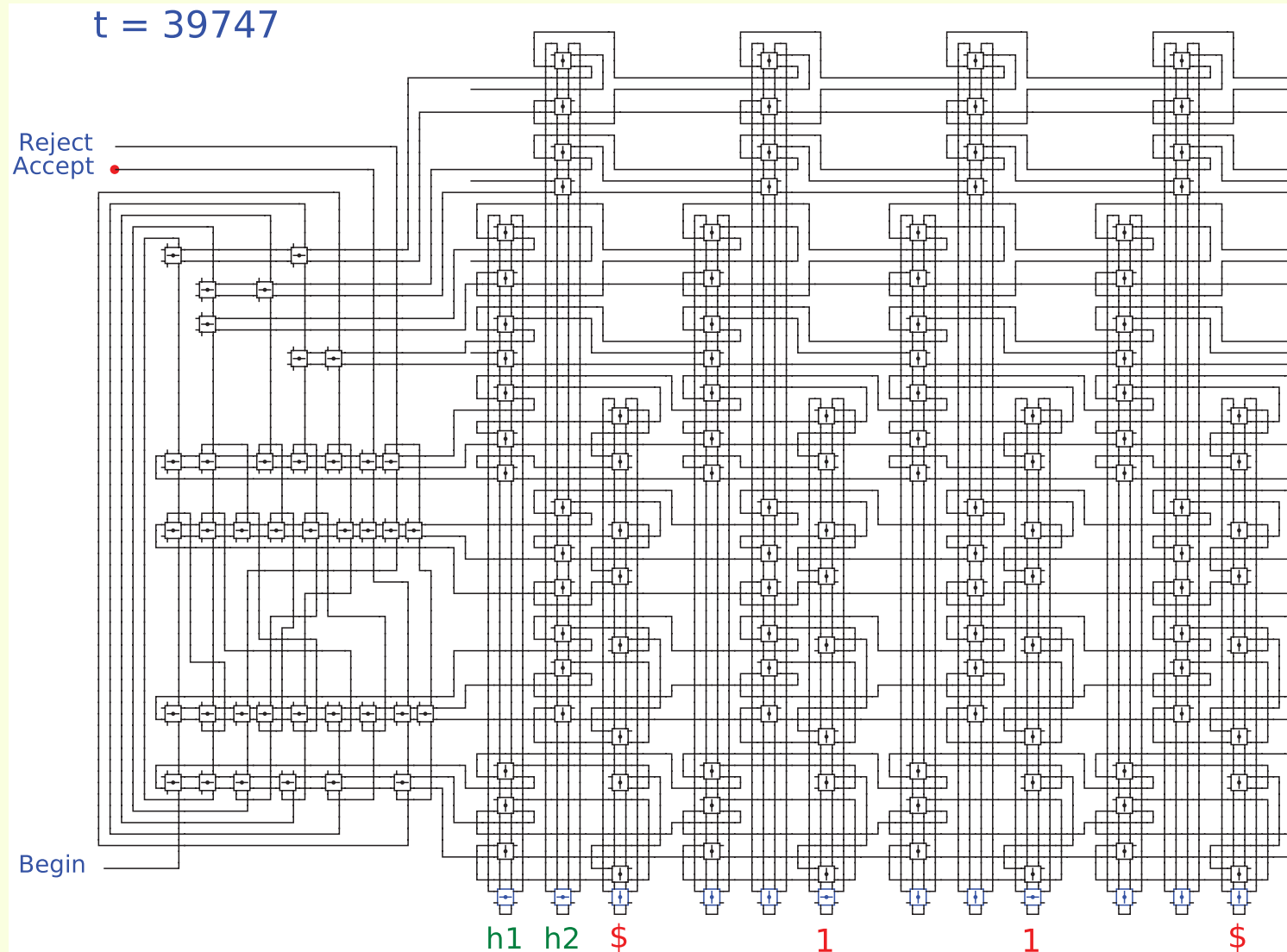
Reversible logic circuit realizing M_{2m}

— Initial configuration for the input $n = 2$ —



Reversible logic circuit realizing M_{2m}

— Final configuration for the input $n = 2$ —



2. Converting a deterministic MFA into a reversible one

A DMFA(k) is simulated by an RDMFA(k)

Theorem 1 For any DMFA(k) M , we can construct an equivalent RDMFA(k) M^\dagger . Hence,

$$\mathcal{L}[\text{RDMFA}(k)] = \mathcal{L}[\text{DMFA}(k)].$$

Remark: $\mathcal{L}[\text{RD1MFA}(k)] \subsetneq \mathcal{L}[\text{D1MFA}(k)]$.

[Kutrib, Malcher, 2012]

Notation:

$\mathcal{L}[\mathcal{M}]$: The class of languages accepted by \mathcal{M} .

1MFA: A one-way MFA

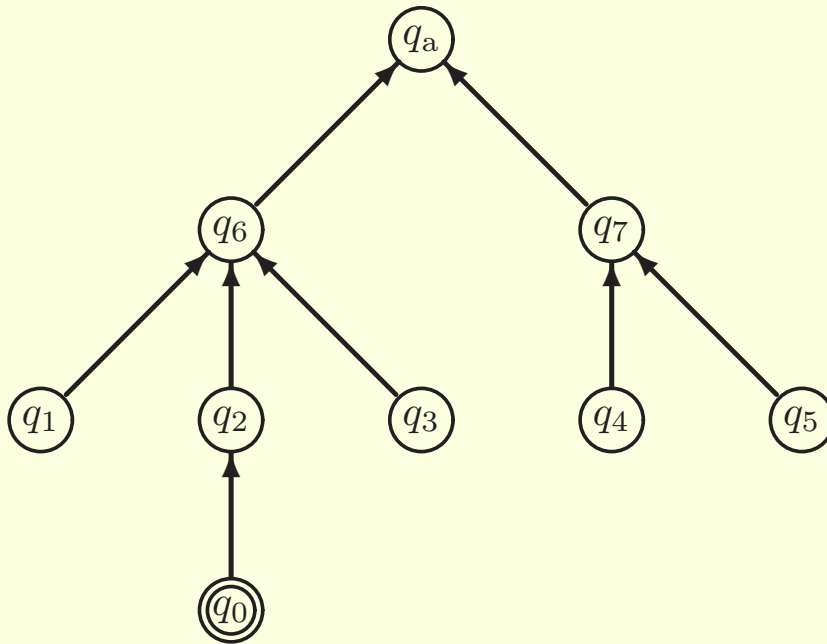
Assumptions on DMFA for proving Theorem 1

- (M1) The initial state q_0 does not appear as the third component of any rule in δ .
- (M2) All the accepting and rejecting states are halting states.
- (M3) Every states other than the initial state appears as the third component of some rule in δ .
- (M4) The DMFA performs read and shift operations alternately.
- (M5) Each head must not go beyond the endmarkers both in forward and backward computation.

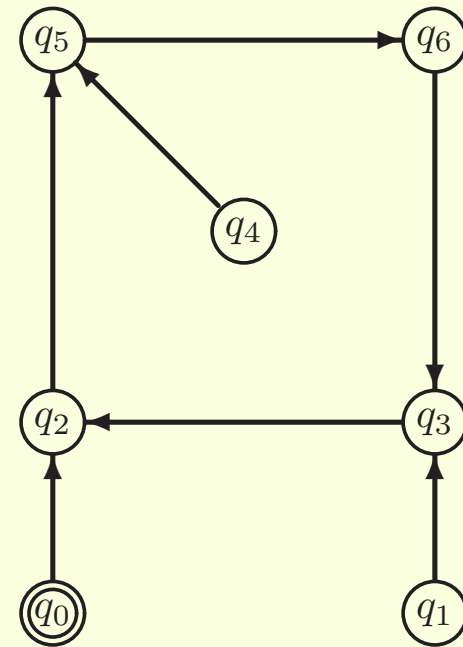
It is easy to modify a DMFA to satisfy them.

Proof outline of Theorem 1

- RDMFA(k) M^\dagger traverses a computation graph of M using additional states.



A case M halts.

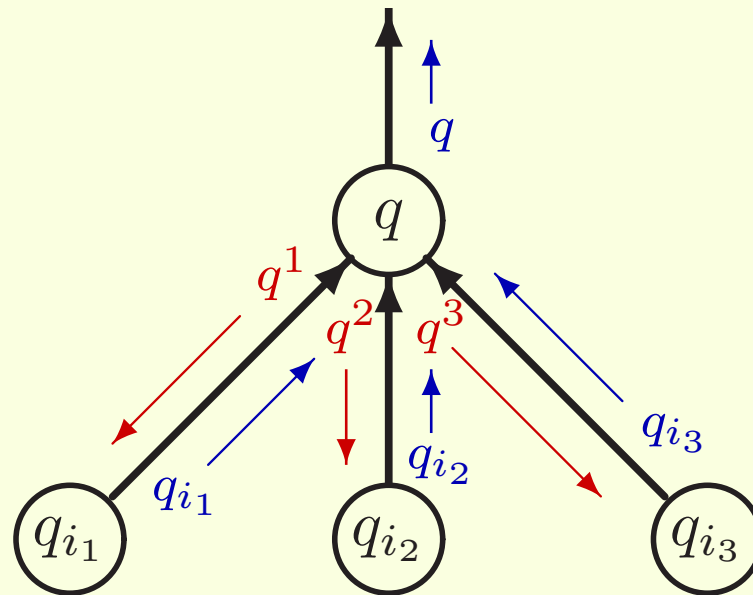


A case M loops.

Note: Each node represents a configuration of M . But, here, only a state of the finite-state control is written.

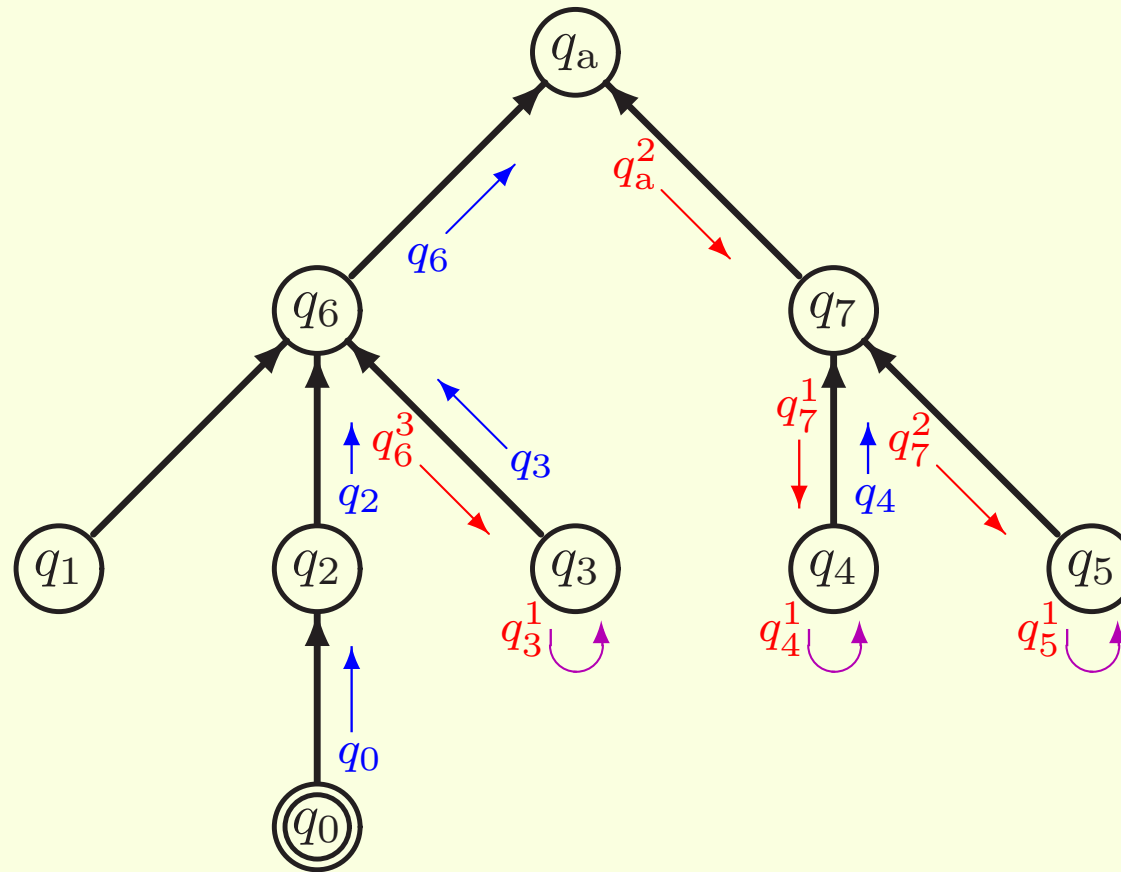
Traversing a computation graph reversibly

- M^\dagger has the following states for each q of M .
 - q is for the forward simulation.
 - q^j is for the backward simulation, where j is used to distinguish the incoming edges.



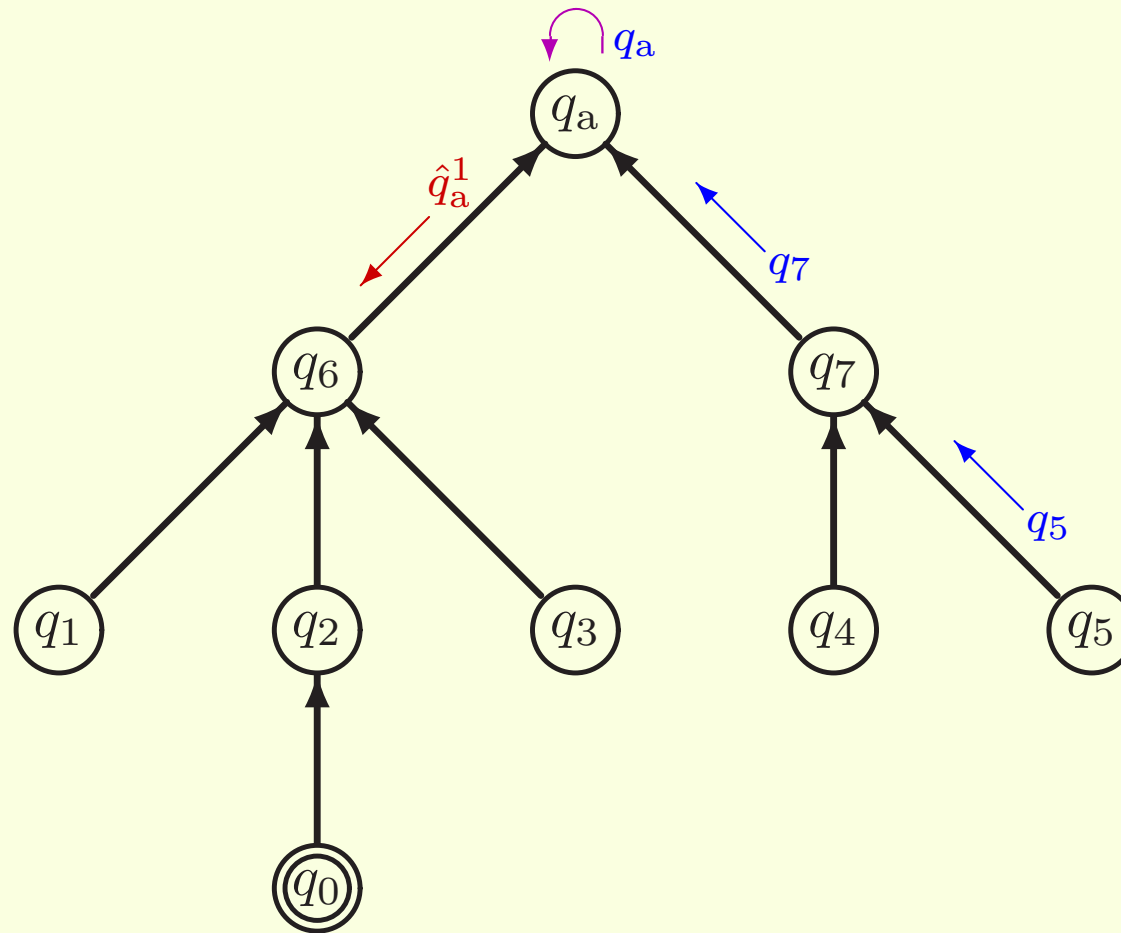
Irreversible transitions of M .

The case M halts in an accepting state (1)



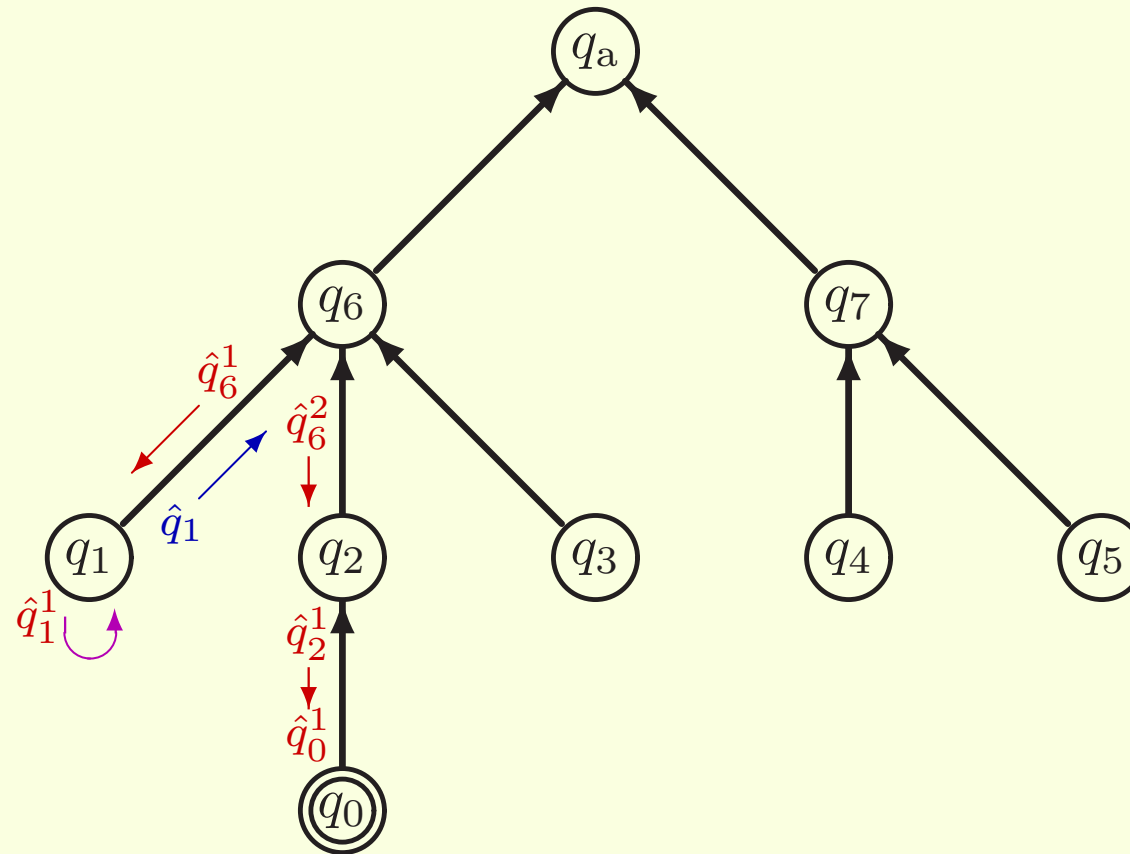
M^\dagger starts to traverse the computation graph from the initial configuration of M .

The case M halts in an accepting state (2)



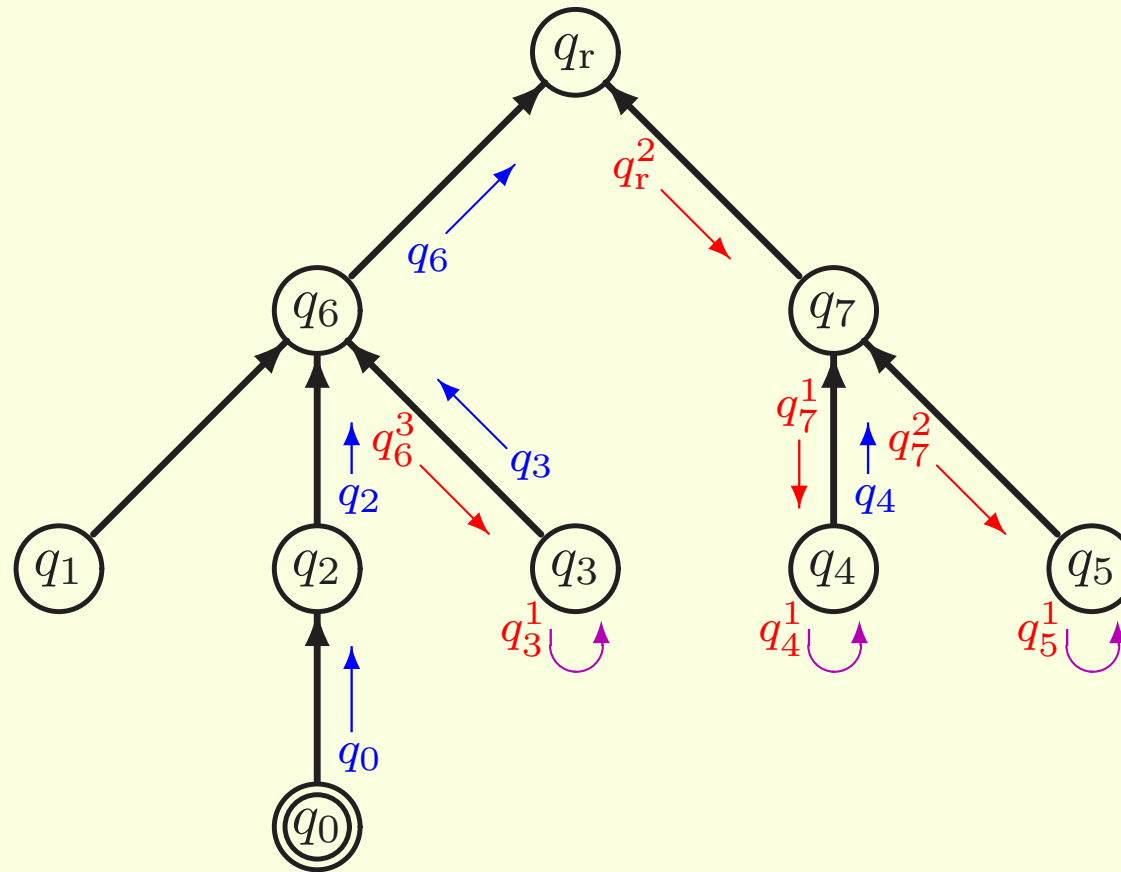
If M enters an accepting state q_a , then M^\dagger keeps the fact by the states of the form \hat{q} .

The case M halts in an accepting state (3)



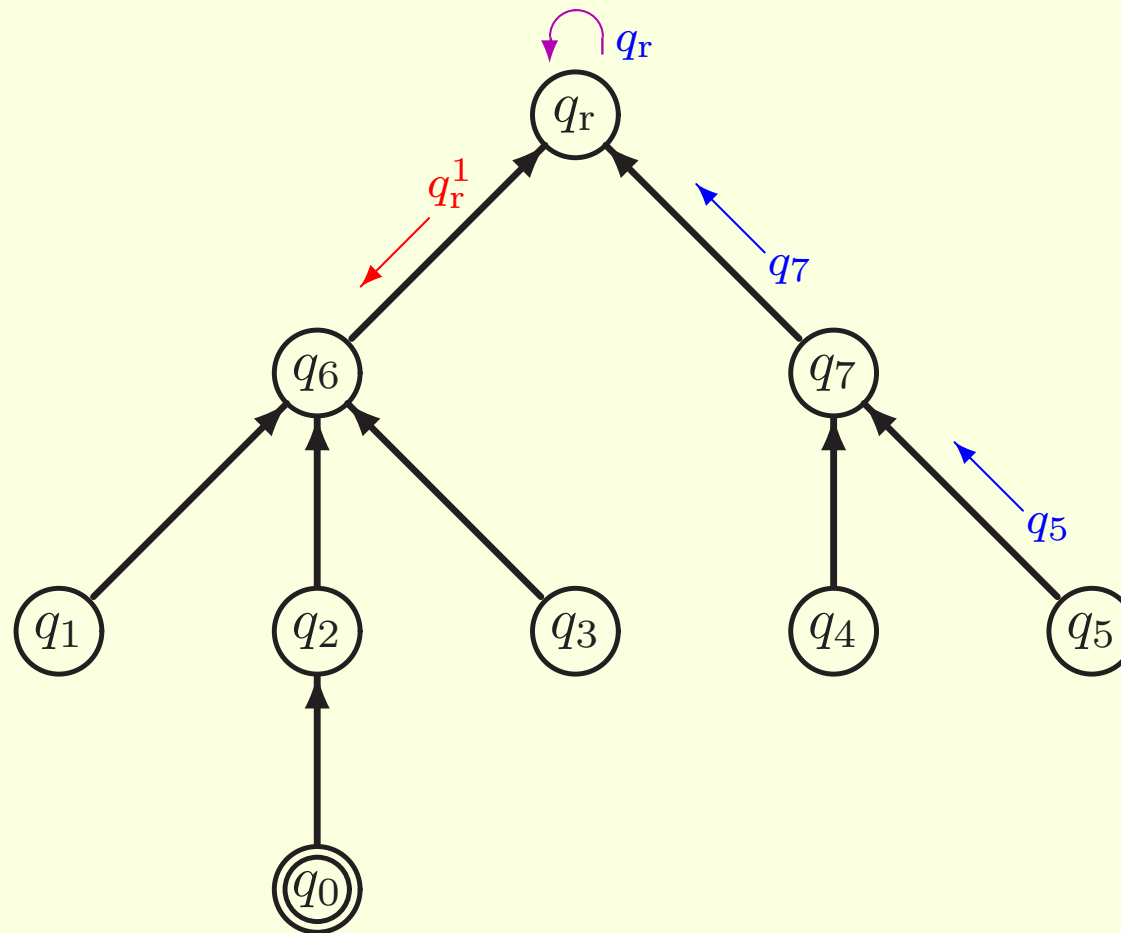
M^\dagger finally goes back to M 's initial configuration in the accepting state \hat{q}_0^1 .

The case M halts in a non-accepting state (1)



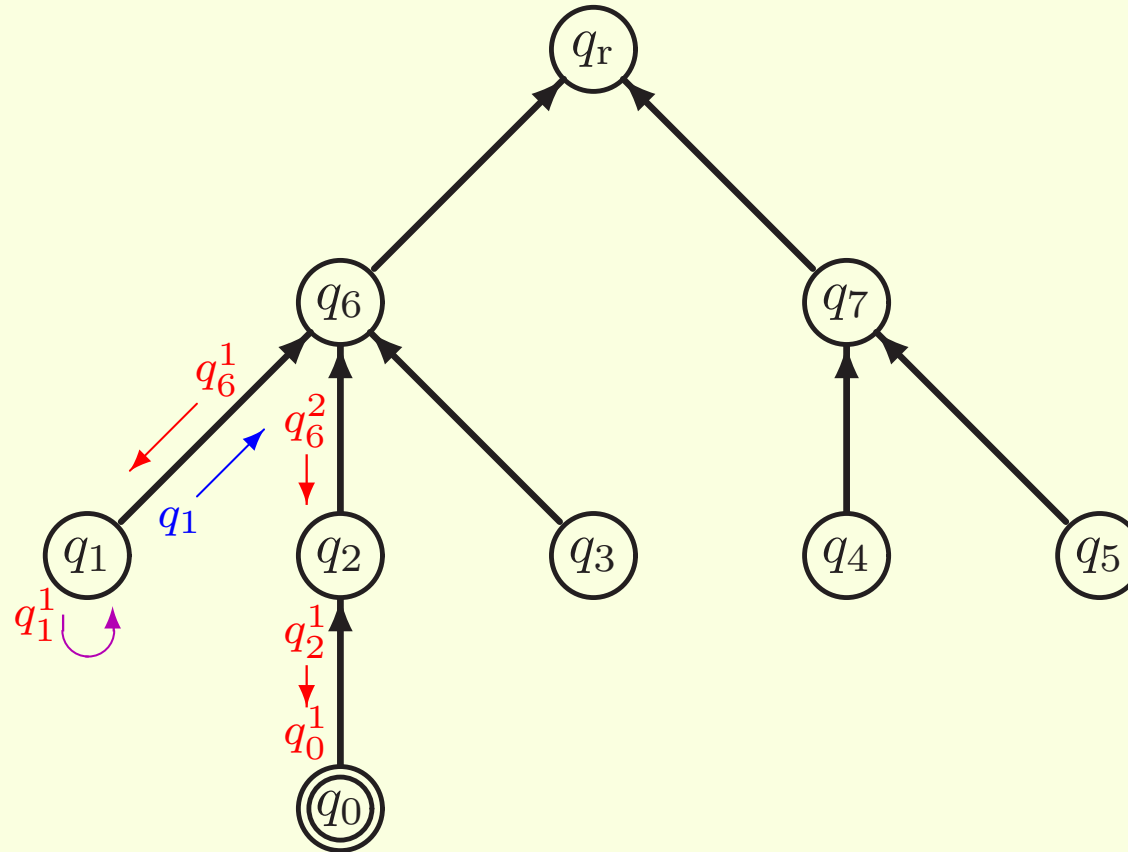
M^\dagger starts to traverse the computation graph from the initial configuration of M .

The case M halts in a non-accepting state (2)



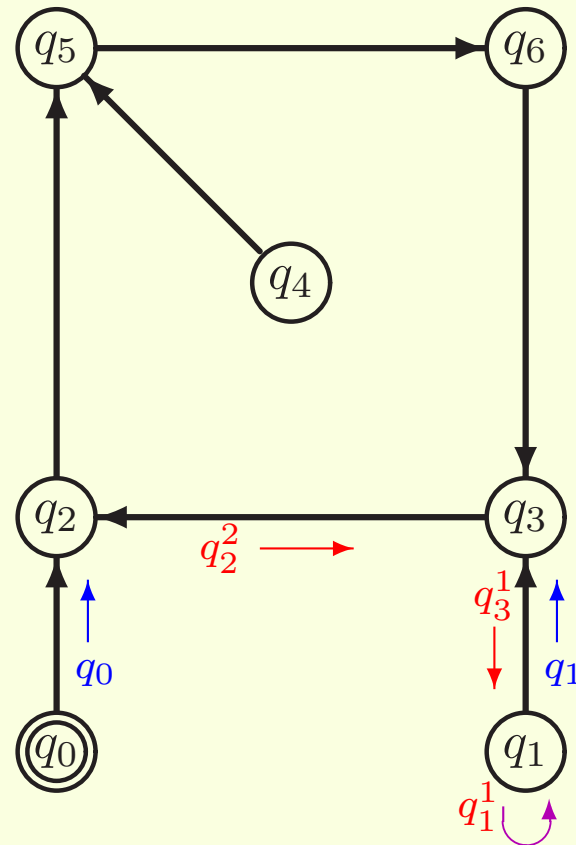
Since M does not enter an accepting state, M^\dagger uses only the states without “ \wedge ”.

The case M halts in a non-accepting state (3)



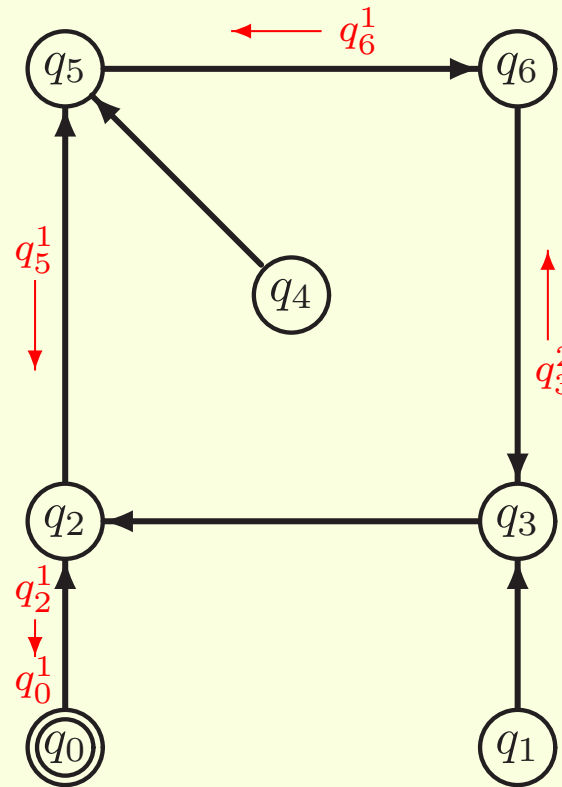
M^\dagger finally goes back to M 's initial configuration in the rejecting state q_0^1 .

The case M loops (1)



M^\dagger starts to traverse the computation graph from the initial configuration of M .

The case M loops (2)



Though it is not a tree, M^\dagger finally goes back to M 's initial configuration in the rejecting state q_0^1 . This is because an RDMFA *always halts*.

An RDMFA always halts

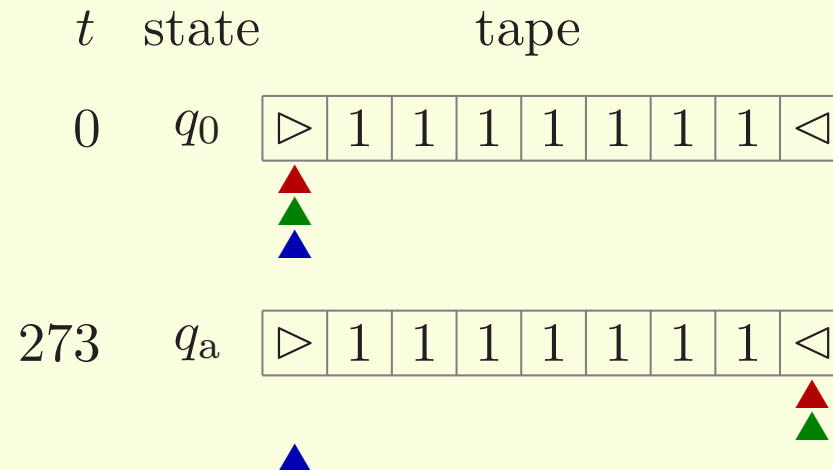
Lemma 1 [Morita, 2011] If M is an RDMFA, then M eventually halts for any input w .

Note: Here, we assume the condition (M1) that the initial state q_0 of M does not appear as the third component of any rule of M (i.e., q_0 has no predecessor state).

Example of an irreversible DMFA(3)

The following irreversible DMFA(3) M_p accepts all strings whose length is a prime number.

$$\begin{aligned}
 M_p &= (Q, \{1\}, 3, \delta, \triangleright, \triangleleft, q_0, \{q_a\}, \{ \}) \\
 Q &= \{q_0, q_1, \dots, q_{16}, q_a\} \\
 \delta &= \{ [q_0, [\triangleright, \triangleright, \triangleright], q_1], [q_1, [0, +, 0], q_2], [q_2, [\triangleright, 1, \triangleright], q_3], [q_3, [0, +, 0], q_4], \\
 & [q_4, [\triangleright, 1, \triangleright], q_5], [q_5, [+ , - , +], q_6], [q_6, [1, 1, 1], q_5], [q_6, [1, \triangleright, 1], q_7], \\
 & [q_6, [\triangleleft, 1, 1], q_9], [q_6, [\triangleleft, \triangleright, 1], q_9], [q_7, [0, +, -], q_8], [q_8, [1, 1, 1], q_7], \\
 & [q_8, [1, 1, \triangleright], q_5], [q_9, [0, +, -], q_{10}], [q_{10}, [\triangleleft, 1, \triangleright], q_{14}], [q_{10}, [\triangleleft, 1, 1], q_{11}], \\
 & [q_{11}, [-, +, -], q_{13}], [q_{12}, [-, 0, 0], q_{13}], [q_{13}, [1, 1, 1], q_{11}], [q_{13}, [1, 1, \triangleright], q_{12}], \\
 & [q_{13}, [\triangleright, 1, \triangleright], q_3], [q_{14}, [0, +, 0], q_{15}], [q_{15}, [\triangleleft, \triangleleft, \triangleright], q_a], [q_{15}, [\triangleleft, 1, \triangleright], q_{16}], \\
 & [q_{16}, [0, -, 0], q_{10}] \}
 \end{aligned}$$

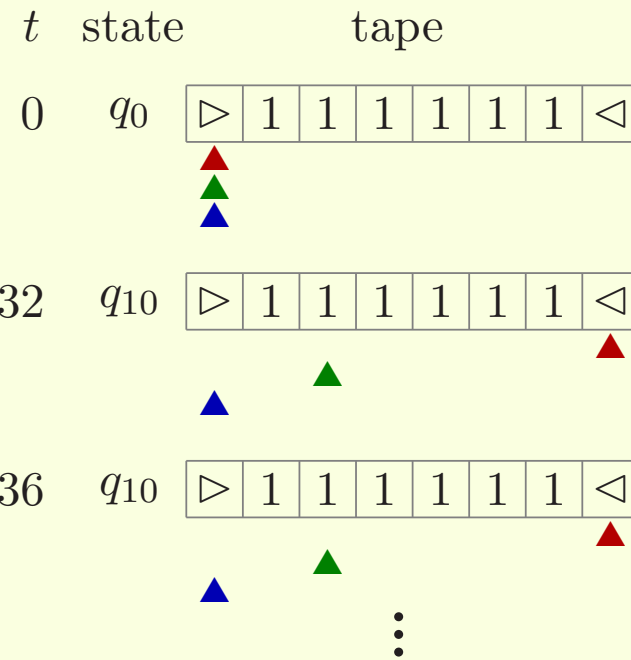
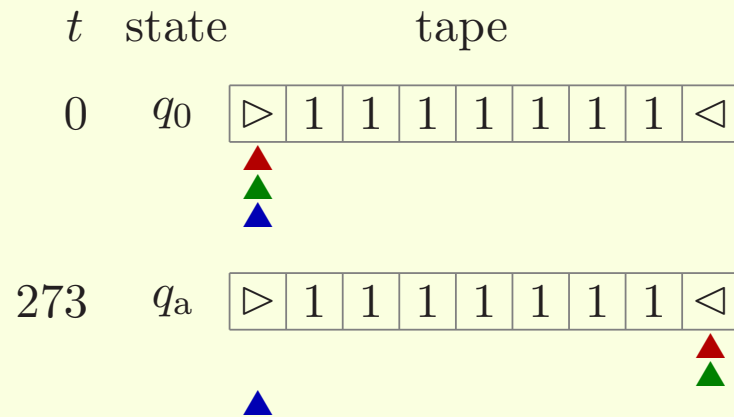


An RDMFA(3) M_p^\dagger that simulates M_p

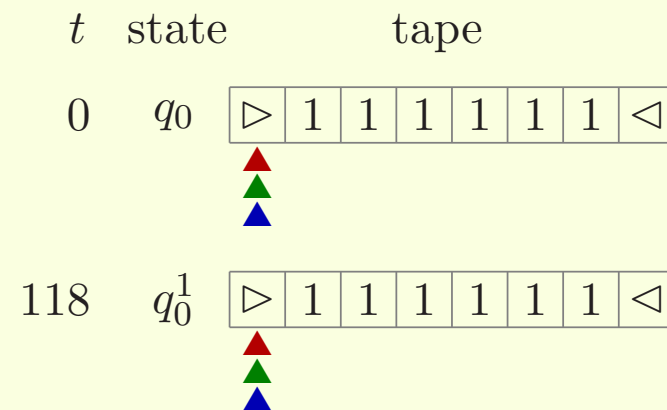
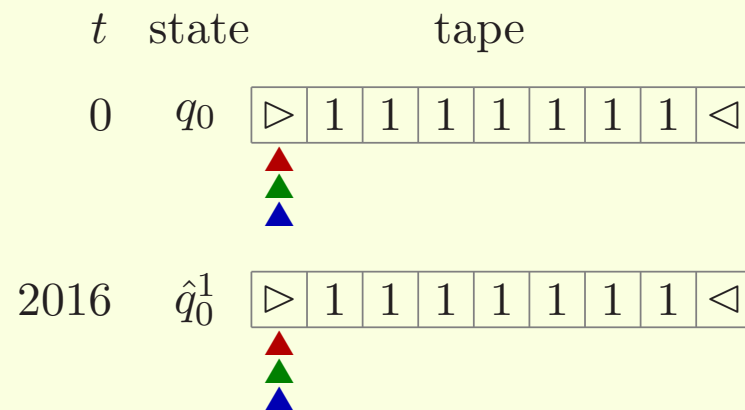
$$\begin{aligned}
 M_p^\dagger &= (Q^\dagger, \{1\}, 3, \delta^\dagger, \triangleright, \triangleleft, q_0, \{\hat{q}_0^1\}, \{q_0^1\}) \\
 Q^\dagger &= \{q, \hat{q}, q^1, \hat{q}^1 \mid q \in Q\} \cup \{q_3^2, q_{10}^2, q_{13}^2, \hat{q}_3^2, \hat{q}_{10}^2, \hat{q}_{13}^2\} \\
 \delta^\dagger &= \delta_1 \cup \dots \cup \delta_6 \cup \hat{\delta}_1 \cup \dots \cup \hat{\delta}_5 \cup \delta_a \cup \delta_r \\
 \delta_1 &= \{ [q_1, [0, +, 0], q_2], [q_3, [0, +, 0], q_4], [q_5, [+ , - , +], q_6], [q_7, [0, +, -], q_8], \\
 &\quad [q_9, [0, +, -], q_{10}^2], [q_{11}, [- , + , -], q_{13}^2], [q_{12}, [- , 0, 0], q_{13}], [q_{14}, [0, +, 0], q_{15}], \\
 &\quad [q_{16}, [0, - , 0], q_{10}] \} \\
 \delta_2 &= \{ [q_0, [\triangleright, \triangleright, \triangleright], q_1], [q_2, [\triangleright, 1, \triangleright], q_3^2], [q_4, [\triangleright, 1, \triangleright], q_5], [q_6, [1, 1, 1], q_5], \\
 &\quad [q_6, [1, \triangleright, 1], q_7], [q_6, [\triangleleft, 1, 1], q_9], [q_6, [\triangleleft, \triangleright, 1], q_9], [q_8, [1, 1, 1], q_7], \\
 &\quad [q_8, [1, 1, \triangleright], q_5], [q_{10}, [\triangleleft, 1, \triangleright], q_{14}], [q_{10}, [\triangleleft, 1, 1], q_{11}], [q_{13}, [1, 1, 1], q_{11}], \\
 &\quad [q_{13}, [1, 1, \triangleright], q_{12}], [q_{13}, [\triangleright, 1, \triangleright], q_3], [q_{15}, [\triangleleft, \triangleleft, \triangleright], q_a], [q_{15}, [\triangleleft, 1, \triangleright], q_{16}] \} \\
 \delta_3 &= \{ [q_2^1, [0, - , 0], q_1^1], [q_4^1, [0, - , 0], q_3^1], [q_6^1, [- , + , -], q_5^1], [q_8^1, [0, - , +], q_7^1], \\
 &\quad [q_{10}^1, [0, - , +], q_9^1], [q_{10}^2, [0, +, 0], q_{16}^1], [q_{13}^1, [+ , - , +], q_{11}^1], [q_{13}^2, [+ , 0, 0], q_{12}^1], \\
 &\quad [q_{15}^1, [0, - , 0], q_{14}^1] \} \\
 \delta_4 &= \{ [q_1^1, [\triangleright, \triangleright, \triangleright], q_0^1], [q_3^1, [\triangleright, 1, \triangleright], q_2^1], [q_3^2, [\triangleright, 1, \triangleright], q_{13}^1], [q_5^1, [\triangleright, 1, \triangleright], q_4^1], \\
 &\quad [q_5^1, [1, 1, 1], q_6^1], [q_5^1, [1, 1, \triangleright], q_8^1], [q_7^1, [1, \triangleright, 1], q_6^1], [q_7^1, [1, 1, 1], q_8^1], \\
 &\quad [q_9^1, [\triangleleft, 1, 1], q_6^1], [q_9^1, [\triangleleft, \triangleright, 1], q_6^1], [q_{11}^1, [\triangleleft, 1, 1], q_{10}^1], [q_{11}^1, [1, 1, 1], q_{13}^1], \\
 &\quad [q_{12}^1, [1, 1, \triangleright], q_{13}^1], [q_{14}^1, [\triangleleft, 1, \triangleright], q_{10}^1], [q_{16}^1, [\triangleleft, 1, \triangleright], q_{15}^1], [q_a^1, [\triangleleft, \triangleleft, \triangleright], q_{15}^1] \} \\
 \delta_5 &= \{ [q_1^1, [\triangleright, \triangleright, 1], q_1], [q_1^1, [\triangleright, \triangleright, \triangleleft], q_1], \dots, [q_{16}^1, [\triangleleft, \triangleleft, \triangleleft], q_{16}] \} \\
 \hat{\delta}_i &= \{ [\hat{p}, \mathbf{x}, \hat{q}] \mid [p, \mathbf{x}, q] \in \delta_i \} \quad (i = 1, \dots, 5) \\
 \delta_6 &= \{ [q_2, [\triangleright, \triangleright, \triangleright], q_2^1], [q_2, [\triangleright, \triangleright, 1], q_2^1], \dots, [q_{15}, [\triangleleft, \triangleleft, \triangleleft], q_{15}^1] \} \\
 \delta_a &= \{ [q_a, [0, 0, 0], \hat{q}_a^1] \} \\
 \delta_r &= \{ \}
 \end{aligned}$$

Simulating the DMFA M_p by the RDMFA M_p^\dagger

M_p :



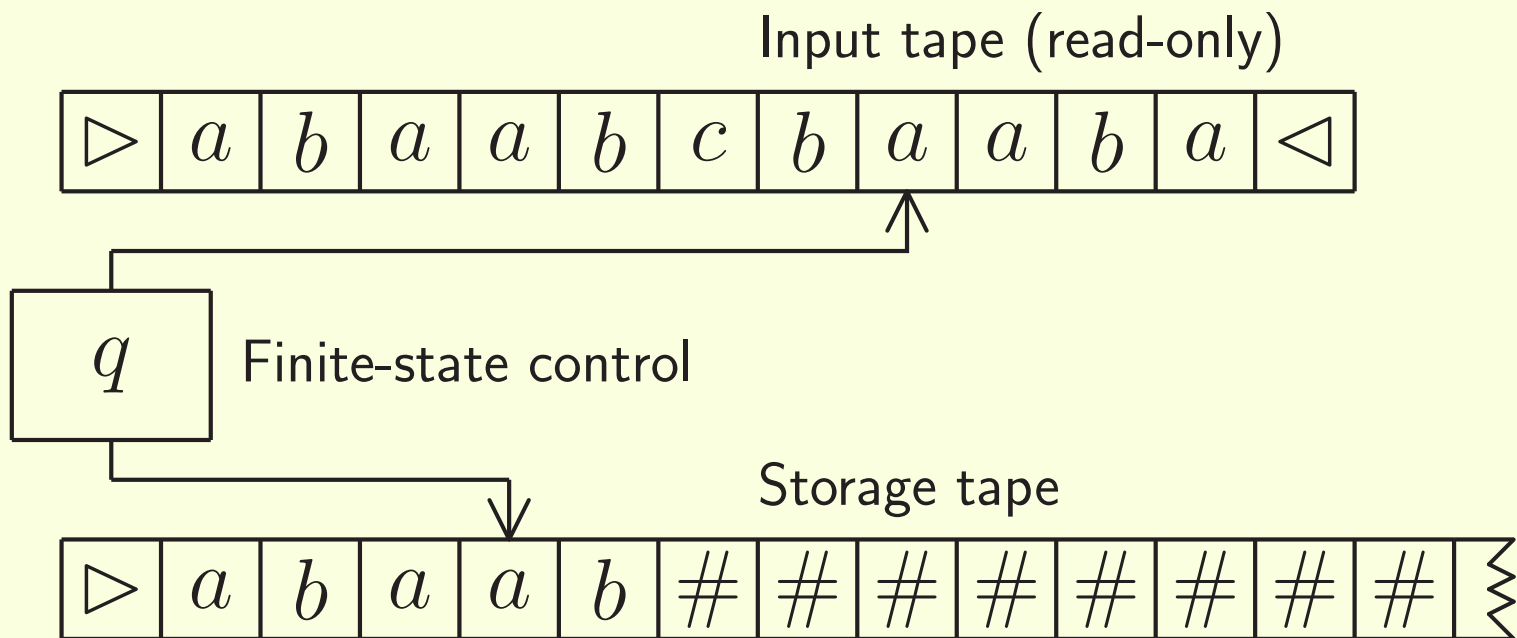
M_p^\dagger :



3. Applying the conversion method to Turing machines

Two-tape Turing machine (TM)

- A model suited for studying space complexity.
- It consists of a finite-state control, a read-only input tape, a storage tape, and two heads.



Relation between $\text{DSPACE}(s(n))$ and $\text{RDSPACE}(s(n))$

Proposition [Lange, McKenzie, Tapp, 2000]

$$\text{DSPACE}(s(n)) = \text{RDSPACE}(s(n))$$

- $(\text{R})\text{DSPACE}(s(n))$: The class of languages accepted by an $s(n)$ space-bounded $(\text{R})\text{DTM}$.
 n is the length of the input, and $s(n)$ is a space function.
- But, the simulation method given by them is rather complex.

The method of converting DMFAs to RDMFAs can be applied to DTMs simply

Theorem 2 For any DTM T , we can construct an equivalent RDTM T^\dagger such that the following holds.

1. T^\dagger uses **exactly the same numbers** of storage tape squares and tape symbols as T . (Thus, it is a bit stronger result than that of Lange et al.)
2. T^\dagger with $w \in \Sigma^*$ always **halts**, provided that T with w uses finitely many storage squares. (We need not know T 's space function $s(n)$.)

An RDTM T_{eq}^\dagger that simulates T_{eq}

$$\begin{aligned}
 T_{eq}^\dagger &= (Q^\dagger, \{a, b\}, \{a, b\}, \delta^\dagger, \triangleright, \triangleleft, q_0, \#, \{\hat{q}_0^1\}, \{q_0^1\}) \\
 Q^\dagger &= \{q, \hat{q}, q^1, \hat{q}^1 \mid q \in Q\} \cup \{q_2^2, q_5^2\} \\
 \delta^\dagger &= \delta_1 \cup \dots \cup \delta_6 \cup \hat{\delta}_1 \cup \dots \cup \hat{\delta}_5 \cup \delta_a \cup \delta_r \\
 \delta_1 &= \{ [q_1, +, +, q_2^2], [q_3, +, 0, q_2], [q_4, -, -, q_5^2], [q_6, -, 0, q_5] \} \\
 \delta_2 &= \{ [q_0, \triangleright, [\triangleright, \triangleright], q_1], [q_2, a, [\#, a], q_1], [q_2, b, [\#, \#], q_3], \\
 &\quad [q_2, \triangleleft, [\#, \#], q_4], [q_5, b, [a, b], q_4], [q_5, a, [a, a], q_6], \\
 &\quad [q_5, \triangleright, [\triangleright, \triangleright], q_a], [q_5, a, [\triangleright, \triangleright], q_6] \} \\
 \delta_3 &= \{ [q_2^1, -, -, q_1^1], [q_2^2, -, 0, q_3^1], [q_5^1, +, +, q_4^1], [q_5^2, +, 0, q_6^1] \} \\
 \delta_4 &= \{ [q_1^1, \triangleright, [\triangleright, \triangleright], q_0^1], [q_1^1, a, [a, \#], q_2^1], [q_3^1, b, [\#, \#], q_2^1], \\
 &\quad [q_4^1, \triangleleft, [\#, \#], q_2^1], [q_4^1, b, [b, a], q_5^1], [q_6^1, a, [a, a], q_5^1], \\
 &\quad [q_a^1, \triangleright, [\triangleright, \triangleright], q_5^1], [q_6^1, a, [\triangleright, \triangleright], q_5^1] \} \\
 \delta_5 &= \{ [q_1^1, \triangleright, [\#, \#], q_1], [q_1^1, \triangleright, [a, a], q_1], \dots, [q_6^1, \triangleleft, [b, b], q_6] \} \\
 \hat{\delta}_i &= \{ [\hat{p}, \mathbf{x}, \hat{q}] \mid [p, \mathbf{x}, q] \in \delta_i \} \quad (i = 1, \dots, 5) \\
 \delta_6 &= \{ [q_2, \triangleright, [\triangleright, \triangleright], q_2^1], [q_2, \triangleright, [\#, \#], q_2^1], \dots, [q_5, \triangleleft, [b, b], q_5^1] \} \\
 \delta_a &= \{ [q_a, 0, 0, \hat{q}_a^1] \} \\
 \delta_r &= \{ \}
 \end{aligned}$$

Concluding remarks

The following relations are proved.

- $\mathcal{L}[\text{RDMFA}(k)] = \mathcal{L}[\text{DMFA}(k)] \quad (k = 1, 2, \dots)$.
- $\mathcal{L}[\text{RDTM}(s(n))] = \mathcal{L}[\text{DTM}(s(n))]$.

The constructed RDTM is garbage-less, and uses the same number of storage tape symbols.

The proposed converting method can be used to many other memory-bounded computing models, e.g. a marker automaton, a space-bounded Turing transducer, etc.