Нікозніма Матн. J. 30 (2000), 117–127

# The Palais-Smale condition for the energy of some semilinear parabolic equations

**Ryo** Ікената

(Recieved January 29, 1999) (Revised April 26, 1999)

ABSTRACT. In this paper we show that all the global solutions for some semilinear parabolic equations naturally contain a Palais-Smale sequence as a subsequence and then we apply a global compactness result due to Struwe [16] to the Palais-Smale sequence. Furthermore, the finite-time blowup problems are discussed.

#### 1. Introduction

In this paper, we are concerned with the following mixed problem to semilinear parabolic equation:

$$u_t(t,x) - \Delta u(t,x) = |u(t,x)|^{p-1} u(t,x), \qquad (t,x) \in (0,T) \times \Omega, \tag{1}$$

$$u(0,x) = u_0(x), \qquad x \in \Omega, \tag{2}$$

$$u|_{\hat{c}\Omega} = 0, \qquad t \in (0,T). \tag{3}$$

Here  $1 and <math>\Omega \subset R^N (N \ge 3)$  is a bounded domain with smooth boundary  $\partial\Omega$ . In the case when 1 we can treatthe lower dimensional case <math>N = 1, 2, but for simplicity we restrict our attention to the above mentioned case. For large initial data  $u_0$  in some sense, it is wellknown that the solution u(t, x) to the problem (1)–(3) blows up in a finite time (see Ikehata-Suzuki [9], Ishii [10], Levine [11], Ôtani [13], Tsutsumi [18], and Payne-Sattinger [14]), meanwhile for small initial data, exponentially decaying solutions are obtained (see [9] and the references therein). In this paper, we are interested in the solutions to (1)–(3) which neither blowup nor decay. We proceed our argument based on the following local well-posedness theorem due to [9] (see also Hoshino-Yamada [7]). In the following,  $\|\cdot\|_q$   $(1 \le q \le \infty)$ means the usual real  $L^q(\Omega)$ -norm.

2000 Mathematics Subject Classification. 35K55

Key words and phrases. Parabolic equation, Palais-Smale sequence, Global compactness result.

Ryo Ikehata

PROPOSITION 1.1. For each  $u_0 \in H_0^1(\Omega)$ , there exists a maximal existence time  $T_m > 0$  (possibly  $T_m = +\infty$ ) such that the problem (1)–(3) has a unique solution  $u \in C([0, T_m); H_0^1(\Omega))$  which becomes classical on  $(0, T_m)$ . Furthermore, if  $T_m < +\infty$ , then

$$\lim_{t\uparrow T_m}\|u(t,\cdot)\|_{\infty}=+\infty,$$

and in particular, in the case when 1 one also has

$$\lim_{t\uparrow T_m} \|\nabla u(t,\cdot)\|_2 = +\infty.$$

Set

$$\begin{aligned} X &= H_0^1(\Omega), \\ J(u) &= \frac{1}{2} \|\nabla u\|_2^2 - \frac{1}{p+1} \|u\|_{p+1}^{p+1}, \\ I(u) &= \|\nabla u\|_2^2 - \|u\|_{p+1}^{p+1}, \\ \mathcal{N} &= \{v \in X \setminus \{0\} \mid I(v) = 0\}, \\ d_p &= \inf_{v \in \mathcal{N}} J(v) = \inf \left\{ \sup_{\lambda \ge 0} J(\lambda v) \mid v \in X \setminus \{0\} \right\} \end{aligned}$$

It is easy to show that the potential depth  $d_p$  is positive (see Sattinger [15]) using the Sobolev continuous embedding  $X \hookrightarrow L^{p+1}(\Omega)$ . The stable and unstable sets are defined as usual:

$$W = \{ u \in X \mid J(u) < d_p, I(u) > 0 \} \cup \{ 0 \},$$
$$V = \{ u \in X \mid J(u) < d_p, I(u) < 0 \}.$$

Furthermore, for later use we define the following notation.

$$E = \{ u \in X \mid -\Delta u = |u|^{p-1} u \text{ in } \Omega, u|_{\partial\Omega} = 0 \},$$
  

$$E^* = \{ u \in \mathcal{D}^{1,2}(\mathbb{R}^N) \mid -\Delta u = |u|^{p-1} u \text{ in } \mathbb{R}^N \},$$
  

$$E^*_+ = \{ u \in E^* \mid u \ge 0 \text{ in } \mathbb{R}^N \},$$
  

$$J_*(u) = \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u(x)|^2 dx - \frac{1}{p+1} \int_{\mathbb{R}^N} |u(x)|^{p+1} dx$$

Here  $\mathscr{D}^{1,2}(\mathbb{R}^N)$  denotes the closure of  $C_0^{\infty}(\mathbb{R}^N)$  with respect to the norm  $\|\nabla u\|_{L^2(\mathbb{R}^N)}$ . In the case when p = (N+2)/(N-2), because of the Sobolev embedding  $S\|u\|_{L^{p+1}(\mathbb{R}^N)} \leq \|\nabla u\|_{L^2(\mathbb{R}^N)}$  for  $u \in \mathscr{D}^{1,2}(\mathbb{R}^N)$ , one also has

Palais-Smale sequence for parabolic equations

$$d^* = d_p = \inf\left\{\sup_{\lambda \ge 0} J_*(\lambda v) \mid v \in \mathcal{D}^{1,2}(\mathbb{R}^N) \setminus \{0\}\right\} = \frac{1}{N}S^N > 0.$$

**REMARK** 1.1. In the case when p = (N+2)/(N-2), it is well-known (Struwe [16]) that the family  $\{u_{\varepsilon}^{*}(x)\}$  defined by

$$u^*_{arepsilon}(x) = rac{[N(N-2)arepsilon^2]^{(N-2)/4}}{[arepsilon^2 + |x|^2]^{(N-2)/2}}, \qquad arepsilon > 0$$

satisfies

$$-\Delta u = |u|^{p-1}u \qquad in \ R^N \tag{4}$$

so that  $E_+^* \setminus \{0\} \neq \emptyset$ .

We start with the following result which we showed quite recently in [9] with regard to the singularity of a global solution to the problem (1)-(3) under the assumptions below: let u(t, x) be a solution to (1)-(3) as in Proposition 1.1. Furthermore, one assumes that

(A.1)  $u_0 \ge 0$ . (A.2) p = (N+2)/(N-2). (A.3)  $\Omega = \{x \in \mathbb{R}^N \mid |x| < 1\}$ . (A.4)  $u(t,x) = u(t,|x|), u_r(t,r) < 0 \text{ on } 0 < r \le 1 \text{ with } r = |x|$ . Finally, assume  $T_m = +\infty$ . For 1 set

$$C_0 = \frac{2(p+1)}{(p-1)} \lim_{t \to +\infty} J(u(t, \cdot)).$$
(5)

Note that  $C_0 \ge 0$  if  $T_m = +\infty$  (see [11]). Then, our results in [9] read as follows.

THEOREM 1.1 ([9]). Assume (A.1)–(A.4). Let u(t, x) be a solution to (1)– (3) on  $[0, T_m)$  as in Proposition 1.1. Suppose  $T_m = +\infty$  and  $C_0 > 0$ . Then, there exists a sequence  $\{t_n\}$  with  $t_n \to +\infty$  as  $n \to +\infty$  such that (i)  $|\nabla u(t_n, x)|^2 \to C_0 \delta_0$  (weakly\*) in  $C_0(\Omega)^*$ , (ii)  $u(t_n, x)^{p+1} \to C_0 \delta_0$  (weakly\*) in  $C_0(\Omega)^*$ , as  $n \to +\infty$ . Here,  $\delta_0$  stands for the usual Dirac measure having a unit mass at the origin.

Since  $C_0 > 0$  if and only if  $u(t, \cdot) \notin (W \cup V)$  for all  $t \ge 0$ , this theorem states that a global orbit  $u(t, \cdot)$  which neither decays nor blowups has a strong singularity at the origin if this kind of solution can be constructed.

In connection with this result, we notice that such a sequence  $\{t_n\}$  constructed in Theorem 1.1,  $\{u(t_n, \cdot)\}$  becomes a Palais-Smale sequence so that the global compactness result due to Struwe [17] can be applied to this

119

functional sequence. So, our first result reads as follows (see also Cerami, Solimini and Struwe [4]):

THEOREM 1.2. Let  $\{u(t_n, \cdot)\} \subset H_0^1(\Omega) \subset \mathcal{D}^{1,2}(\mathbb{R}^N)$  be a sequence as in Theorem 1.1. Then there exist a subsequence of  $\{u(t_n, \cdot)\}$ , relabelled again as  $\{u(t_n, \cdot)\}$ , an integer  $k \in \mathbb{N}$ , a sequence of radii  $\{R_n^i\}$  with  $\lim_{n \to +\infty} R_n^i = +\infty$  $(1 \le i \le k)$  such that

$$\lim_{n \to +\infty} \left\| \nabla (u(t_n, \cdot) - \sum_{i=1}^k u_n^i) \right\|_{L^2(\mathbb{R}^N)} = 0,$$
$$\lim_{t \to +\infty} J(u(t, \cdot)) = \lim_{n \to +\infty} J(u(t_n, \cdot)) = k J_*(\omega) = \frac{p-1}{2(p+1)} C_0 > 0,$$
$$\lim_{n \to +\infty} \| \nabla u(t_n, \cdot) \|_2^2 = k \| \nabla \omega \|_{L^2(\mathbb{R}^N)}^2,$$

where

$$u_n^i(x) = (R_n^i)^{(N-2)/2} \omega(R_n^i x) \quad (1 \le i \le k), \qquad n = 1, 2, \dots$$

together with  $\omega(x) = u_1^*(x)$  defined in Remark 1.1.

REMARK 1.2. It is easy to see that  $J_*(\omega) = d^*$  (least energy level) follows. Therefore, one has  $\frac{p-1}{2(p+1)}C_0 = kd^*$  so that if, in particular, k = 1, then  $\lim_{t \to +\infty} J(u(t, \cdot)) = d^*$ , i.e., the energy  $J(u(t, \cdot))$  for a solution  $u(t, \cdot)$  of (1)–(3) may attain its least energy level as in the subcritical case. Similarly, since  $\|\nabla \omega\|_{L^2(\mathbb{R}^N)}^2 = S^N$  in the present case, from Lemma 2.1 below it follows that  $C_0 = kS^N$ .

REMARK 1.3. Under the assumptions  $\Omega = \text{star-shaped}$  and  $u_0(x) \ge 0$ , one can get the similar results as in the radial case above with a slight modification. In the case when  $u_0$  changes sign, however, even if  $\Omega$  is star-shaped, one needs to modify the results above in accordance with the results in [16] (for more general case, see the proof of Proposition 2.1).

The next result is concerned with the case when 1 .It seems unknown that any global solutions to (1)–(3) naturally contain a subsequence which is relatively compact in X in the subcritical case. Our second result reads as follows:

THEOREM 1.3. Let 1 and <math>u(t,x) be a solution on  $[0, T_m)$  as in Proposition 1.1. If  $T_m = +\infty$ , then there exists a sequence  $\{t_n\}$  with  $t_n \to +\infty$  as  $n \to +\infty$  such that  $\{u(t_n, \cdot)\}$  becomes relatively compact in X

so that there exists an element  $u_{\infty} \in E$  such that  $u(t_n, \cdot) \to u_{\infty}$  in X as  $n \to +\infty$ along a subsequence.

REMARK 1.4. If  $C_0 > 0$ , then one has  $u_{\infty} \in E \setminus \{0\}$  in Theorem 1.3. Moreover, such a sequence  $\{t_n\}$  is constructed in the same way as in Theorem 1.2. On the other hand, unfortunately, the results in Theorem 1.3 are weaker than that of [3] or [13] in the sense that their results state the relative compactness in  $H_0^1(\Omega)$  of the trajectory  $\{u(t, \cdot)\}$ .

#### 2. Palais-Smale sequence

Reviewing some results concerning Theorem 1.1 due to [9] we shall construct some Palais-Smale sequences of a global solution to the problem (1)–(3), and then we will prove Theorems 1.2 and 1.3.

First, suppose  $1 and <math>T_m = +\infty$  in Proposition 1.1. Since its solution satisfies the energy identity:

$$J(u(t,\cdot)) + \int_0^t \|u_t(s,\cdot)\|_2^2 ds = J(u_0) \quad \text{all } t \ge 0,$$
(6)

this implies that the function  $t \mapsto J(u(t, \cdot))$  is monotone decreasing so that  $C_0 \ge 0$  (see (5)) is meaningfull. Letting  $t \to +\infty$  in (6), the improper integral  $\int_0^\infty ||u_t(s, \cdot)||_2^2 ds$  is finitely determined. Therefore, there exists a sequence  $\{t_n\}$  with  $t_n \to +\infty$  as  $n \to +\infty$  such that

$$\lim_{n\to+\infty}\|u_t(t_n,\cdot)\|_2=0.$$

In fact this sequence  $\{t_n\}$  is given in [9] for the proof of Theorem 1.1.

Next, multiplying the both sides of (1) by u(t,x) and integrating it over  $\Omega$ , we have

$$(u_t(t,\cdot), u(t,\cdot)) = -I(u(t,\cdot)), \tag{7}$$

where  $(f,g) = \int_{\Omega} f(x)g(x)dx$ . Due to [3], it is true that  $||u(t,\cdot)||_2 \le C$  for all  $t \ge 0$  for some constant C > 0. Therefore, one has

$$|I(u(t,\cdot))| \le C ||u_t(t_n,\cdot)||_2 \quad \text{for all } n \in N.$$

Letting  $n \to +\infty$ , it follows that

$$\lim_{n \to +\infty} I(u(t_n, \cdot)) = 0.$$
(8)

On the other hand, the identity holds:

$$J(u) = \frac{p-1}{2(p+1)} \|\nabla u\|_2^2 + \frac{1}{p+1} I(u).$$
(9)

So, from (9) with  $u = u(t_n, \cdot)$  and (7)-(8) we find that

#### **Ryo** Ικεήλτα

LEMMA 2.1. Let  $u(t, \cdot)$  be as in Proposition 1.1. If  $T_m = +\infty$ , then there exists a sequence  $\{t_n\}$  with  $t_n \to +\infty$  as  $n \to +\infty$  such that

$$\lim_{n \to +\infty} \|u_t(t_n, \cdot)\|_2 = 0,$$
$$\lim_{n \to +\infty} \|\nabla u(t_n, \cdot)\|_2^2 = C_0,$$
$$\lim_{n \to +\infty} \|u(t_n, \cdot)\|_{p+1}^{p+1} = C_0.$$

From this lemma, one obtains the next one:

LEMMA 2.2. Let  $u(t, \cdot)$  be a local solution constructed in Proposition 1.1. If  $T_m = +\infty$ , then there exists a Palais-Smale sequence to the problem (1)–(3).

**PROOF.** Let  $\{t_n\}$  be as in Lemma 2.1. Then, it follows that

$$J(u_0) \ge J(u(t_n, \cdot)) \longrightarrow \frac{p-1}{2(p+1)} C_0 \ge 0 \qquad \text{as } n \to +\infty.$$
 (10)

Furthermore, for such a sequence, since  $J \in C^1(X, R)$ , by equation (1) we have

$$J'(u(t_n,\cdot))[v] = -(u_t(t_n,\cdot)), v)$$

for each  $v \in X$ , where  $J'(u) \in X^*$  means the usual Fréchet-derivative of J at  $u \in X$ . By this equality and the Schwarz inequality together with the Poincaré inequality one gets:

$$|J'(u(t_n, \cdot))[v]| \le C_1 ||u_t(t_n, \cdot))||_2 ||\nabla v||_2$$

which implies

$$\|J'(u(t_n,\cdot))\|_{H^{-1}(\Omega)} \to 0 \qquad (n \to +\infty), \tag{11}$$

where  $C_1 > 0$  is a Poincaré constant. We find that  $\{u(t_n, \cdot)\}$  is a Palais-Smale sequence because of (10) and (11).

In particular, in the case when 1 one gets the following compactness result.

LEMMA 2.3. Suppose  $1 . Let <math>u(t, \cdot)$  be a global (i.e.,  $T_m = +\infty$ ) solution to (1)–(3) as in Proposition 1.1. Then, the sequence  $\{u(t_n, \cdot)\}$  constructed in Lemma 2.1 becomes relatively compact in X.

**PROOF.** For simplicity, one sets  $u_n = u(t_n, \cdot)$ . Multiplying the both sides of (1) by  $v \in X$  and integrating it over  $\Omega$ , we have

$$|(\nabla u_n, \nabla v) - (f(u_n), v)| = |(u_t(t_n, \cdot), v)| \le C_1 ||u_t(t_n, \cdot)||_2 ||\nabla v||_2,$$
(12)

where  $f(v)(x) = |v(x)|^{p-1}v(x)$ . From Lemma 2.1 it follows that for an arbitrary  $\varepsilon > 0$ , there exists a natural number  $N_0$  such that for all  $n \ge N_0$ ,

$$\|u_t(t_n,\cdot)\|_2 < \frac{\varepsilon}{C_1}.$$
(13)

Because of (12) and (13), we have

$$|(\nabla u_n, \nabla v) - (f(u_n), v)| \le \varepsilon \|\nabla v\|_2 \le \varepsilon^2 + \frac{1}{4} \|\nabla v\|_2^2.$$
(14)

On the other hand, it follows from the Hölder inequality that

$$|(f(u_n), v)| \le ||u_n||_{p+1}^p ||v||_{p+1}.$$
(15)

By takin as  $v = u_n - u_m$  in (14) and (15), we can proceed the following estimates:

$$\begin{aligned} \|\nabla u_n - \nabla u_m\|_2^2 &= \int_{\Omega} [\nabla u_n \nabla (u_n - u_m) - f(u_n)(u_n - u_m)] dx \\ &- \int_{\Omega} [\nabla u_m \nabla (u_n - u_m) - f(u_m)(u_n - u_m)] dx \\ &+ \int_{\Omega} (f(u_n) - f(u_m))(u_n - u_m) dx \\ &\leq \frac{1}{2} \|\nabla u_n - \nabla u_m\|_2^2 + 2\varepsilon^2 + (\|u_n\|_{p+1}^p + \|u_m\|_{p+1}^p) \|u_n - u_m\|_{p+1} \end{aligned}$$

for all  $m, n \ge N_0$ . This implies

$$\|\nabla u_n - \nabla u_m\|_2^2 \le 4\varepsilon^2 + 2(\|u_n\|_{p+1}^p + \|u_m\|_{p+1}^p)\|u_n - u_m\|_{p+1}$$
(16)

for all  $m, n \ge N_0$ .

Now, since  $\{u_n\}$  is bounded in X, by the compact embedding of  $X \hookrightarrow L^{p+1}(\Omega)$  we can assume that  $u_n \to u_\infty$  in  $L^{p+1}(\Omega)$  for some  $u_\infty$  as  $n \to +\infty$ . Together with (16), we find that  $\{u_n\}$  becomes a Cauchy sequence in X.  $\Box$ 

Now, we are in a position to prove Theorems 1.2 and 1.3.

PROOF OF THEOREM 1.2. Basically, this is a direct consequence of [16] (Theorem 3.1, p. 184) and Lemma 2.2. Under the framework of Theorem 1.1, however, one has  $E = \{0\}$ ,  $x_n^i = 0$   $(1 \le i \le k)$  in use of [16] and note that the solution u(x) for the equation (4) is uniquely determined (up to scaling and translation) such as  $u(x) = u_1^*(x) = \omega(x)$ .

We shall state the outline of its proof. Indeed, set

$$Q_n(t) = \int_{|x| < t} (|\nabla u(t_n, x)|^2 + |u(t_n, x)|^{p+1}) dx.$$

# **Ryo** Ικεήλτα

Then, for each  $v \in (0, S^N)$ , we can find a real number  $R_n = R_n(v) > 1$  such that  $Q_n\left(\frac{1}{R_n}\right) = v$ . Set  $u_n(x) = R_n^{-(N-2)/2} u(t_n, x/R_n)$ . Then, since the embedding

$$\mathscr{D}_{rad}^{1,2}(\mathbb{R}^N) \hookrightarrow L^{\infty}\left(\left\{\frac{1}{\mathbb{R}} \le |x| \le \mathbb{R}\right\}\right)$$
(17)

is compact for each R > 1, it will follow that  $u_n \to \omega \in E_+^* \setminus \{0\}$  (weakly) in  $\mathscr{D}_{rad}^{1,2}(\mathbb{R}^N)$  as  $n \to +\infty$  along a subsequence (c.f., [9] or [12]). Here,  $\mathscr{D}_{rad}^{1,2}(\mathbb{R}^N) = \{v \in \mathscr{D}^{1,2}(\mathbb{R}^N) \mid v(x) = v(|x|)\}.$ 

In fact, if  $\omega \equiv 0$ , then it follows from Lemma 2.1 and the compact embedding (17) that

$$u_n(x)^{p+1} \to C_0 \delta_0$$
 (weakly\*) in  $C_0(\mathbb{R}^N)^*$ 

as  $n \to +\infty$ . On the other hand, if we choose  $\phi \in C_0^{\infty}(\mathbb{R}^N)$ , with  $\phi = 1$  on  $B_1(0)$  and  $0 \le \phi \le 1$  on  $\mathbb{R}^N$ , then one can estimate as follows:

$$0 \le \int_{\mathbb{R}^N} \phi(x) u_n(x)^{p+1} dx \le \nu + \int_{|x|\ge 1} \phi(x) u_n(x)^{p+1} dx = \nu + o(1)$$

as  $n \to +\infty$ . This implies  $C_0 \le v$  which contradicts the fact  $v \in (0, S^N)$  and  $C_0 \ge S^N$ .

Next, set  $v_n(x) = u(t_n, x) - R_n^{(N-2)/2} \omega(R_n x)$ . By iterating this procedure for the sequence  $\{v_n\} \subset \mathcal{D}_{rad}^{1,2}(\mathbb{R}^N)$ , one can prove Theorem 1.2 similarly to the usual global compactness argument (c.f. [16] or [17]).

**PROOF OF THEOREM 1.3.** The first half is a direct consequence of Lemma 2.3. In order to prove  $u_{\infty} \in E$ , note the following estimates:

$$\|f(u) - f(v)\|_{1+(1/p)} \le p(\|u\|_{p+1} + \|v\|_{p+1})^{p-1} \|u - v\|_{p+1}$$
  
for all  $u, v \in L^{p+1}(\Omega)$ ,

and

$$\begin{split} |(f(u(t_n, \cdot)) - f(u_{\infty}), \phi)| &\leq ||f(u(t_n, \cdot)) - f(u_{\infty})||_{1+(1/p)} ||\phi||_{p+1} \\ \text{for each } \phi \in C_0^{\infty}(\Omega), \end{split}$$

where  $\{u(t_n, \cdot)\}$  is a sequence constructed in the first half. By combining these estimates with Lemma 2.1 and the Sobolev embedding  $X \hookrightarrow L^{p+1}(\Omega)$ , one obtains the desired result.

From the view point of the Palais-Smale condition, we have the following result.

COROLLARY 2.1. Let 1 and <math>u(t,x) be a global solution constructed in Proposition 1.1, i.e.,  $T_m = +\infty$ . If  $C_0 = 0$ , then the sequence  $\{u(t_n, \cdot)\}$  given in Lemma 2.1 becomes relatively compact, and in fact,  $u(t, \cdot) \to 0$  in X as  $t \to +\infty$ .

**PROOF.** If  $C_0 = 0$ , then, from Lemma 2.1 it follows that  $\lim_{n \to +\infty} \|\nabla u(t_n, \cdot)\|_2 = 0$ . On the other hand, it is well-known that the stable set W is a bounded neighbourhood of 0 in X. Thus,  $u(t_{n_0}, \cdot) \in W$  for some  $t_{n_0}$ . This implies that  $\|\nabla u(t, \cdot)\|_2 = O(e^{-\alpha t})$  as  $t \to +\infty$  (see [9]).

From Theorem 1.1 and corollary 2.1 with p = (N+2)/(N-2), one can say that it depends on the least energy level  $(p-1)C_0/2(p+1)$  whether the Palai-Smale condition holds or not to the sequence  $\{u(t_n, \cdot)\}$  in Lemma 2.1.

Now, we apply Theorem 1.3 and Lemma 2.2 for the finite time blowup problem concerning (1)-(3). First, as a consequence of [16] one obtains the following lemma.

LEMMA 2.4. Let  $\Omega$  be a bounded smooth domain and p = (N+2)/(N-2). Then, for all  $v \in E$ , one has  $J(v) \in \{0\} \cup (d^*, +\infty)$ , and also, for each  $w \in E^* \setminus \{0\}$ , one has  $J_*(w) \in \{d^*\} \cup (2d^*, +\infty)$ .

The following result gives a kind of alternative proof of [13] concerning blowup problem.

PROPOSITION 2.1. Let 1 and <math>u(t,x) be a local solution of (1)–(3) on  $[0, T_m)$  constructed in Proposition 1.1. If  $u(t_0, \cdot) \in V$  for some  $t_0 \in [0, T_m)$ , then  $T_m < +\infty$ .

**PROOF.** First, we shall deal with the case when 1 .Suppose  $T_m = +\infty$ . Then, it follows from Theorem 1.3 that there exists a Palais-Smale sequence  $\{u(t_n, \cdot)\}$  to the problem (1)-(3) and  $u_{\infty} \in E$  such that  $u(t_n, \cdot) \to u_{\infty}$  in X. On the other hand, it is well-known (see [8]) that  $u(t, \cdot) \in V$  for all  $t \in [t_0, \infty)$ . If  $u_{\infty} = 0$ , then  $u(t_m, \cdot) \in W$  with some  $t_m$  since W is a neighbourhood of 0 in X and this contradicts the fact that  $W \cap$  $V = \emptyset$ . Thus,  $u_{\infty} \in E \setminus \{0\}$ . Since the function  $t \mapsto J(u(t, \cdot))$  is monotone, one obtains  $J(u(t_n, \cdot)) \ge J(u_{\infty}) \ge d_p$  which contradicts  $u(t_n, \cdot) \in V$  with large  $t_n$ . Next, with we are concerned the critical case p =(N+2)/(N-2). Suppose  $T_m = +\infty$ . Obviously,  $C_0 > 0$ . Then, from Lemma 2.2 and Theorem 3.1 of [16], p. 184 there exist a Palais-Smale sequence  $\{u(t_n, \cdot)\}, k \in \mathbb{N}, u^0 \in \mathbb{E}, \text{ and } u^i \in \mathbb{E}^* \setminus \{0\} \ (1 \le i \le k) \text{ such that}$ 

$$\lim_{n\to+\infty} J(u(t_n,\cdot)) = \lim_{t\to+\infty} J(u(t,\cdot)) = J(u^0) + \sum_{i=1}^k J_*(u^i).$$

**Ryo** Ικεήλτα

By Lemma 2.4 and the monotone decreasingness of a function  $t \mapsto J(u(t, \cdot))$ , one finds that

$$J(u(t, \cdot)) \ge d^*$$
 for all  $t \ge 0$ .

This contradicts also  $u(t, \cdot) \in V$  for all  $t \ge t_0$ .

# Acknowledgement

The author wishes to thank Prof. T. Ogawa, Kyushu Univ., and Prof. M. Iida, Iwate Univ., for their valuable comments. Moreover, the author would like to thank Prof. T. Suzuki, Osaka Univ., for his helpful conversations and encouragement. Finally, the author also wishes to thank the referee for his careful reading and kind helpful advice.

## References

- H. Brezis and L. Nirenberg. Positive solutions of nonlinear elliptic equations involving critical Sobolev exponents. Comm. Pure Appl. Math. 36 (1983), 437–477.
- [2] V. Benci and G. Cerami. Existence of positive solutions of the equation  $-\Delta u + a(x)u = u^{(N+2)/(N-2)}$  in  $\mathbb{R}^N$ . J. Func. Anal. 88 (1990), 90-117.
- [3] T. Cazenave and P. L. Lions. Solutions globales d'equations de la chaleur semilineaires. Comm. Partial Diff. Eq. 9 (1984), 955-978.
- [4] G. Cerami, S. Solimini and M. Struwe. Some existence results for superlinear boundary value problems involving critical exponents. J. Func. Anal. 69 (1986), 289–306.
- Y. Giga. A bound for global solutions of semilinear heat equations. Comm. Math. Phys. 103 (1986), 415–421.
- [6] D. Henry. Geometric Theory of Semilinear Parabolic Equations. Lecture notes in Math. 840, Springer-Verlag, 1981.
- [7] H. Hoshino and Y. Yamada. Solvability and smoothing effect for semilinear parabolic equations. Funk. Ekva. 34 (1991), 475–494.
- [8] R. Ikehata and T. Suzuki. Stable and unstable sets for evolution equations of parabolic and hyperbolic type. Hiroshima Math. J. 26 (1996), 475-491.
- [9] R. Ikehata and T. Suzuki. Semilinear parabolic equations involving critical Sobolev exponent: local and asymptotic behavior of solutions. to appear in Diff. Int. Equations.
- [10] H. Ishii. Asymptotic stability and blowing-up of solutions of some nonlinear equations. J. Diff. Eq. 26 (1977), 291–319.
- [11] H. A. Levine. Some nonexistence and instability theorems of solutions of formally parabolic equations of the form  $Pu_t = -Au + F(u)$ . Arch. Rat. Mech. Math. 51 (1973), 371–386.
- [12] P. L. Lions. The concentration-compactness principle in the calculus of variations: the locally compact case. Part I, Ann. I.H.P. Analyse Nonlinéaire 1 (1984), 109-145 and Part II 1 (1984), 223-283.
- [13] M. Otani. Existence and asymptotic stability of strong solutions of nonlinear evolution equations with a difference term of subdifferentials. Colloq. Math. Soc. Janos Bolyai, Qualitative Theory of Differential Equations 30, North-Holland, Amsterdam, 1980.

126

- [14] L. E. Payne and D. H. Sattinger. Saddle points and unstability of nonlinear hyperbolic equations. Israel J. Math. 22 (1975), 273-303.
- [15] D. H. Sattinger. On global solution of nonlinear hyperbolic equations. Arch. Rat. Mech. Math. 30 (1968), 148-172.
- [16] M. Struwe. Variational Methods. A Series of Modern Surveys in Mathematics 34, Springer-Verlag, 1996.
- [17] M. Struwe. A global compactness result for elliptic boundary value problems involving limitting nonlinearities. Math. Z. 187 (1984), 511–517.
- [18] M. Tsutsumi. On solutions of semilinear differential equations in a Hilbert space. Math. Japon. 17 (1972), 173-193.

Department of Mathematics Faculty of School Education Hiroshima University Higashi-Hiroshima, 739-8524 Japan e-mail: rikehat@sed.hiroshima-u.ac.jp